



Implementation of Fuzzy Logic Controller for Step-Up Converter Combining KY and Buck-Boost Converter with Soft-Switching Technic

Arya .P.R¹, Saritha Sathyan²

PG Student [PE], Dept. of EEE, Sree Narayana Gurukulam College of Engineering, Kadayiruppu, Kerala, India¹

Associate Professor, Dept. of EEE, Sree Narayana Gurukulam College of Engineering, Kadayiruppu, Kerala, India²

ABSTRACT: In this paper, a novel voltage gain enhanced step-up converter is presented. This converter is the combination of KY and synchronous BUCK-BOOST converter. Here the voltage gain enhancement is done by using coupled inductor with turns ratio and one charging pump. The output current of the converter is nonpulsating, hence the voltage stress across the output capacitor is less. Soft –switching technic is implemented for reducing the switching losses. Switch on time ZVS and switch off time ZCS will happen. In this project, a closed loop DC-DC KY and BUCK-BOOST converter circuit was designed and simulated using MATLAB SIMULINK based on a topological circuit. In this simulation, the circuit was tested with PI controller &FUZZY controller. PI controller and Fuzzy Logic Controllers are designed and implemented in the circuit with calculated duty cycle of the MOSFET. The outcome has indicated better performance for KY and BUCK-BOOST step-up converter with FLC controller.

KEYWORDS: KY converter, Synchronous BUCK-BOOST converter, Coupled inductor, Charging pump, High Voltage Gain, Soft-switching, Fuzzy Logic Controller.

I. INTRODUCTION

Renewable energy sources have experienced a rapid development in recent years. These systems employ with micro sources like PV, fuel cells etc. PV cells to produce high voltage but there exist severe problems like shadowing effects, short circuit which significantly reduces its efficiency. In order to overcome such unfavourable conditions this type of micro source energy is applied to the high step up converter to produce high voltage and fulfil the demands. In rapid progress of communication and computing gadgets DC-DC converters are employed for various devices like amplifiers, personal digital assistant (PDA), MP3 players, blue tooth devices etc., which need high voltage to obtain enough output power and voltage amplitude.

This converter is the combination of one KY and one Buck-Boost converter. Here the voltage gain can be enhanced by synchronous buck-boost converter and coupled inductor. A synchronous buck-boost converter is similar to buck boost converter with the diode is replaced by a MOSFET switch. The main objective is to improve the voltage gain of the step-up converter and also to reduce switching loss. Switching losses can be reduced by adding resonance converter. Further the voltage drift problem is reduced using closed loop control of the proposed converter with fuzzy logic controller.

II. LITERATURE SURVEY

There are many techniques to obtain voltage gain. Few of the techniques are discussed below. Voltage multiplier cell [1] method is suitable only for small voltage gain because if we need to increase the output voltage, we need to increase the corresponding multiplier stage. This will make the circuit more complex. Another method of obtaining voltage gain is by using transformers with dc-dc converters [2]. This converter can boost the voltage gain by increasing the turns ratio. This leads to increase in leakage inductance which will reduce the overall efficiency of the converter. Cascaded converters is a very simple method to obtain a high voltage gain [3]. But this structure consists of larger number of

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

components. Hence the circuit will become complex and also the final output stage suffers a high voltage stress. Luo converter is the one of the voltage boosting converter [4], but it needs two or more inductors and also possesses the drawback of right half plane zero

The KY buck-boost converter is a recently introduced step-up converter. This converter produces a high voltage gain. Step-up converter is a combination of one charging pump and a coupled inductor with turns ratio [5]. This voltage gain can be achieved either by adjusting the duty cycle or by turns ratio i.e., the duty cycle and the turns ratio are independent. This converter always works in CCM, Keeping the output current non-pulsating, hence voltage stress across the output capacitor will be suppressed but the switching loss is high. Switching loss can be reduced by adding resonance circuit which is a good solution for switching loss.

A novel soft switching is proposed and applied to the KY converter. Such a soft switching needs only one additional small inductor and one additional small capacitor, and this occupies only small space in the circuit of the KY converter. [6]

A fuzzy logic controller for the conventional DC-DC converters has been reported in [7]. The FLC for all the converters has produced lesser output voltage start-up overshoots and lower output voltage ripple as compared to PI controller.

III. CIRCUIT DESCRIPTION

Fig 1 shows the KY and Buck-BOOST converter with soft switching technic. Prior to taking up this section, for the convenience of analysis, this converter contains two MOSFET switches namely S_1 and S_2 along with their body diodes S_{D1} and S_{D2} . A coupled inductor with primary turns N_p and secondary turns N_s which is used to obtain high voltage gain. Capacitor C_1 is energy transferring capacitor and capacitor C_2 is charge pump capacitor. Three diodes D_1, D_2 and D_3 . At the output side, one output inductor L_o , one output capacitor C_o is connected. The load is signified as R_o . The input voltage and output voltages are represented as V_i and V_o respectively. A resonance inductor L_r and a resonance capacitor C_r which is used for soft switching purpose. So the voltages across switches are zero during turn off period and current through the switches are zero during the turn on period. Besides, since the energy-transferring capacitor C_1 , operating based on the charge pump principle, are quickly charged to some voltages within a very short time.

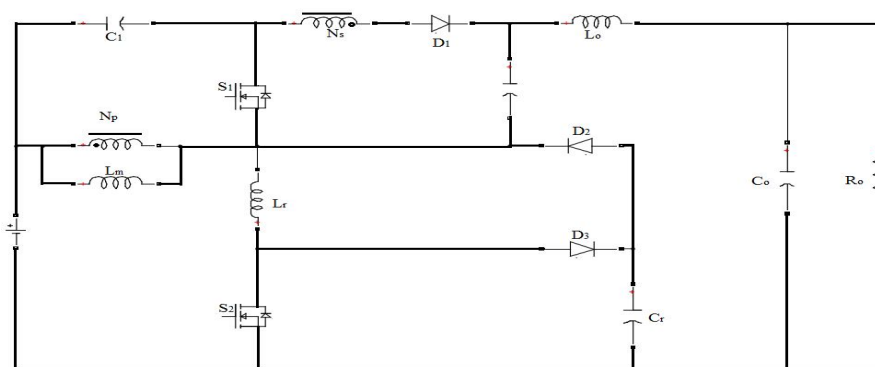


Fig 1: Soft-Switched KY and Buck-Boost Converter

IV. PRINCIPLE OF OPERATION

Coupling coefficient k is equal to one, i.e., the leakage inductor is absent. The following analysis contains the description of the power flow path for each mode, along with the corresponding equations and voltage gain. Essentially, there are five operating modes in the proposed converter. Moreover, the gate driving signals v_{gs1} and v_{gs2} of the two switches S_1 and S_2 have the duty cycles of D and $(1 - D)$ respectively. In addition, the input current is denoted by i_i , the current through the N_p winding is signified by i_{NP} , the current through the N_s winding is signified by i_{NS} , the current through L_m is denoted by i_{Lm} , the current through L_o is denoted by i_{L_o} , and the current through R_o is

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

indicated by I_o , the current through L_r is denoted by i_{Lr} , the current through C_r is denoted by i_{Cr} . On the other hand, the voltage across L_m or the voltage across the N_p winding is represented by v_{NP} , the voltage across the N_s winding is signified by v_{Ns} , the voltage across C_1 is represented by V_{C1} , the voltage across C_2 is represented by V_{C2} , the voltage across C_r is denoted by V_{Cr} and the voltage across L_o is denoted by v_{Lo} .

MODE I

In this mode switch S_1 is turned on and switch S_2 is turned off. Two power flow path is there, one is energy provided to load and another is charging the resonance capacitor through resonance inductor. Thus the voltage across capacitor C_r increases slowly which is responsible for zero voltage turn off switch S_2 . First, $-V_{C1}$ voltage is imposed on N_p . Due to this negative voltage, L_m will be demagnetized.

The voltage induced across the secondary winding equal to,

$$V_{Ns} = -V_{C1} \times \frac{N_s}{N_p} \tag{1}$$

Due to this negative voltage induced in the secondary winding, diode D_1 becomes reverse-biased.

Voltage across the load inductor becomes,

$$V_{Lo} = V_i + V_{C1} + V_{C2} - V_o \tag{2}$$

The voltage induced across the load inductor is positive value, thus causing L_o to be magnetized. And provides energy to the load V_o ,

$$V_o = V_i + V_{Np} + V_{C2} + V_{Lm} \tag{3}$$

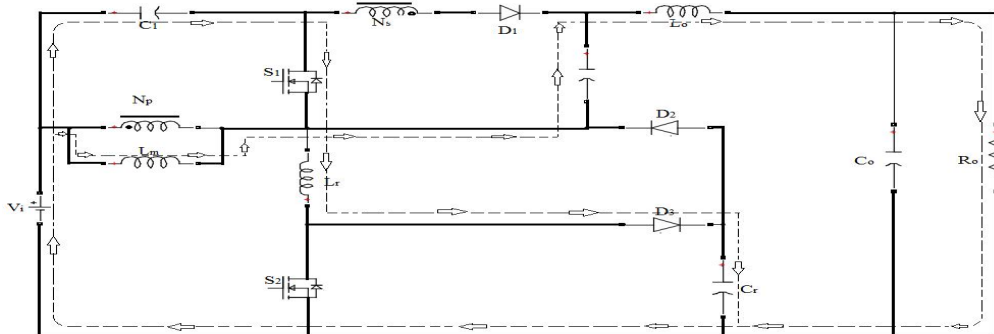


Fig 2: Mode I Operation of the Converter

MODE II

Switch S_1 is still on and switch S_2 is off. When the voltage across resonance capacitor C_r increases and it exceeds the voltage across the energy transferring capacitor C_1 , the direction of current becomes reverse. The switch S_1 conducts through the anti-parallel diode. This is shown in figure 3

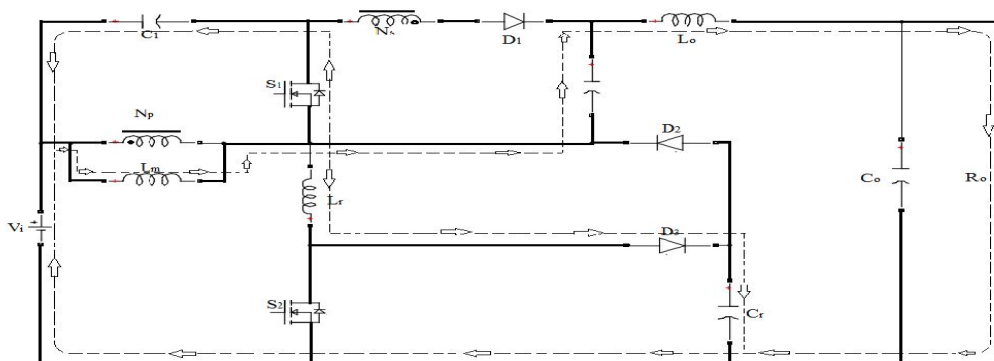


Fig 3: Mode II Operation of the Converter

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

MODE III

When the resonance capacitor C_r charged to its extreme value, that voltage is hold on V_{Cr} . Direction of power flow shown in the fig 4

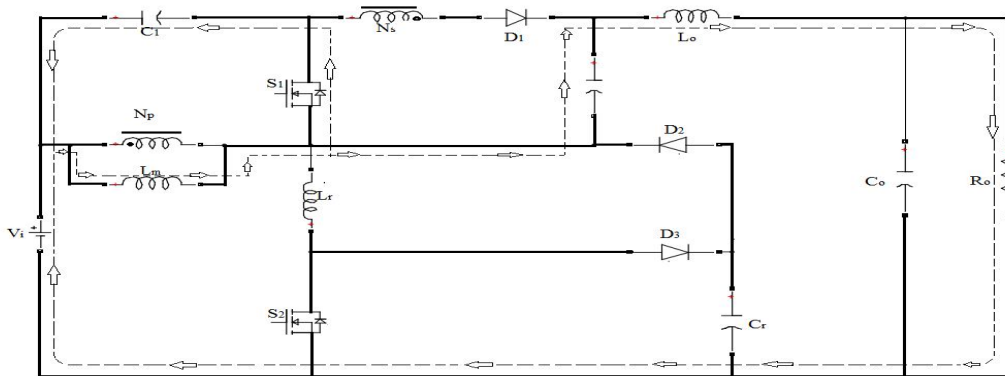


Fig 4: Mode III Operation of the Converter

MODE IV

Mode IV is shown in fig 4.5. In this mode of operation, the input voltage is imposed on N_p , thus causing magnetizing inductor to be magnetized. The switch S_1 is turned off and switch S_2 is turned on. Due to the presence of L_r , the current through switch S_2 increases slowly which is responsible for zero current turn on of switch S_2 . The energy stored in the resonance capacitor C_r is discharged slowly through diode D_2 and resonance inductor L_r . This voltage comes across switch S_1 . Thus zero voltage turned off will occur.

The voltage induced across the secondary winding equal to,

$$V_{Ns} = V_i \times \frac{N_s}{N_p} \quad (4)$$

Due to this negative voltage D_1 becomes forward biased; C_2 is charged to,

$$V_{c2} = V_i + V_{c1} + \left(V_i \times \frac{N_s}{N_p} \right) \quad (5)$$

And the voltage across L_0 ,

$$V_{L0} = V_{c2} - V_0 \quad (6)$$

ie, V_{L0} is negative value which makes L_0 demagnetized. Hence output voltage becomes,

$$V_0 = V_{c2} + V_{L0} \quad (7)$$

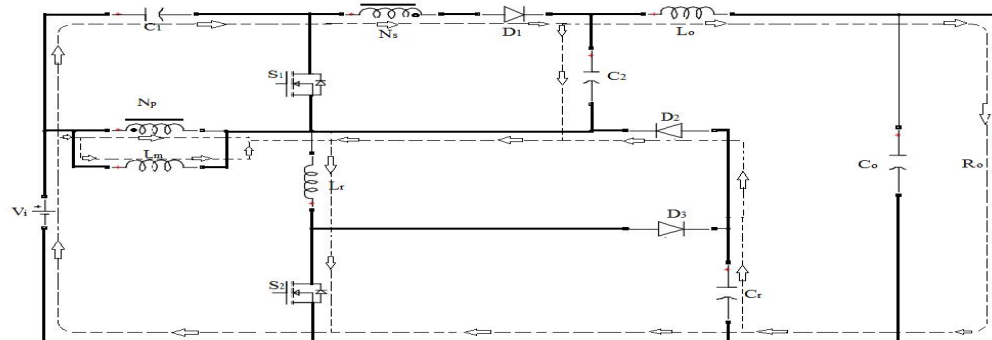


Fig 5: Mode IV Operation of the Converter

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

MODE V

In this mode, switch S_2 is still on and switch S_1 is off. The capacitor C_r completely discharges and the power flow is shown in fig 6.

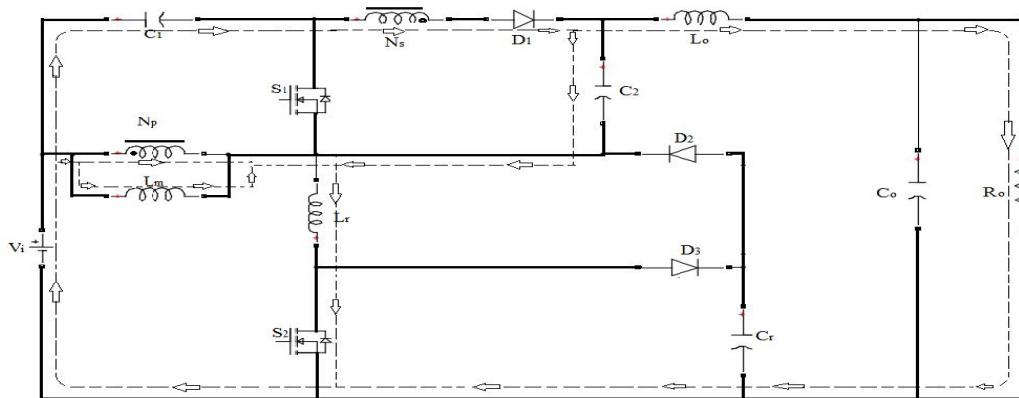


Fig 6: Mode V Operation of the Converter

V. FUZZY LOGIC CONTROLLER

Fuzzy logic system is an intelligent system which is easy to understand, simple to design and better than using the other type of controller. In Fuzzy logic controller, better tuning of fuzzy will provide better output. This logic allows modelling of complex systems by combining alternative way of thinking using a higher level of abstraction. The variables of fuzzy logic are described for the control algorithm which influences the system variables and a rule table. The gain is defined as a division between the input voltage and average output voltage value.

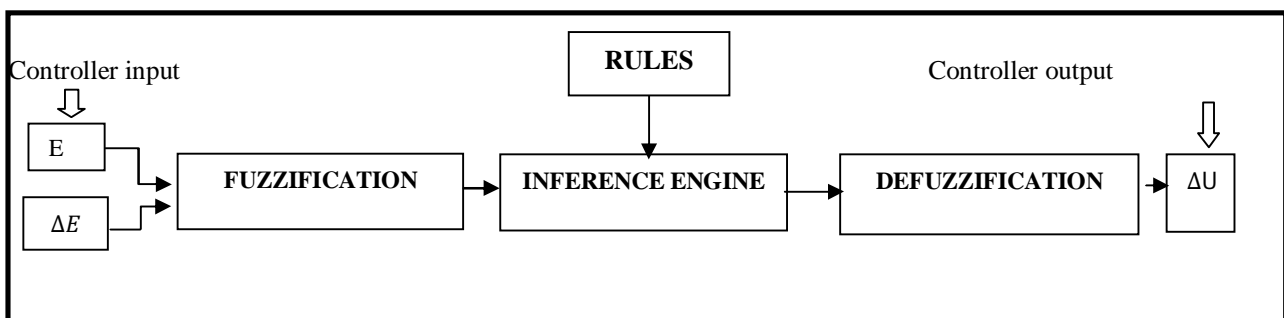


Fig7: Block diagram of FLC

The block diagram of fuzzy logic controller (FLC) is shown in fig.7. It consists of three main blocks: fuzzification, inference engine and defuzzification. The two FLC input variables are the error E and change in error ΔE . Depending on membership functions and the rules FLC operates. Mamdani type fuzzy logic scheme is used here.

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

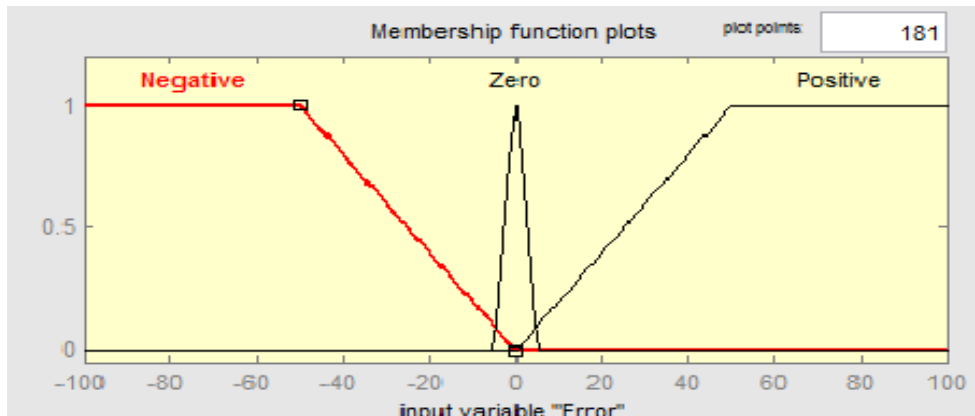


Fig 8:Membership function for error

There are three membership functions for the input variable error. Fig. 8 shows the membership functions of input variable error.

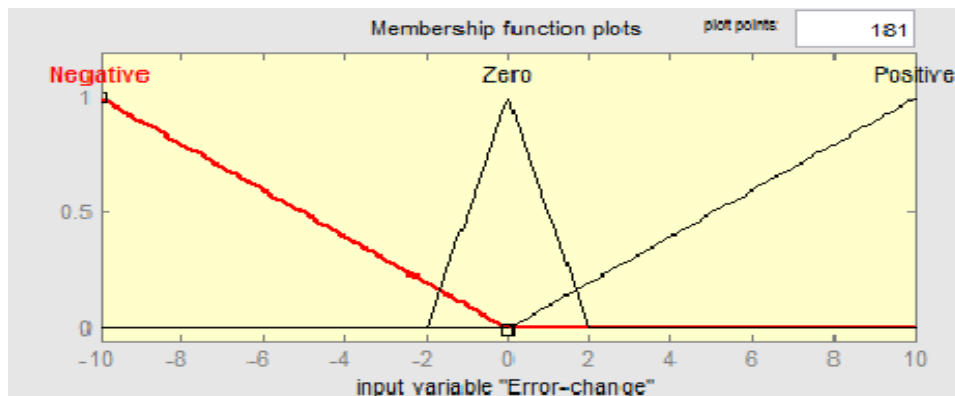


Fig 9: Membership function for deltaerror

There are three membership functions for the input variable deltaerror. Fig. 9 shows the membership functions of input variable deltaerror.

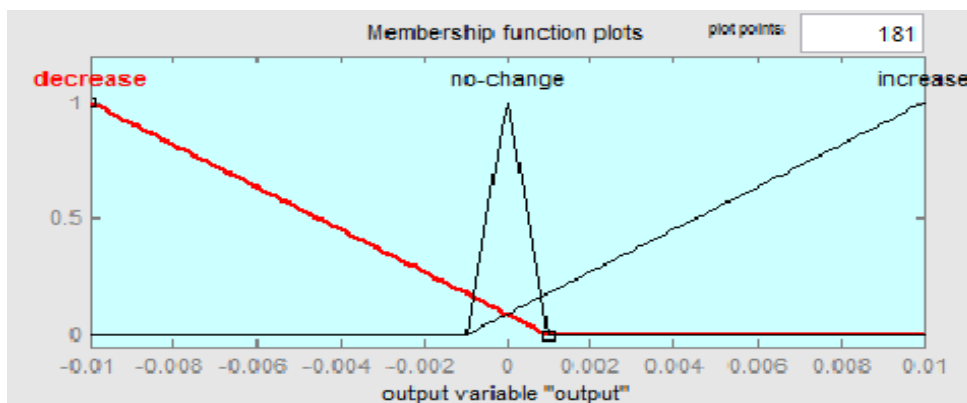


Fig 10: Plot of membership function for output

There are three membership functions for the output variable. Fig. 10 shows the membership functions of output variable.

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

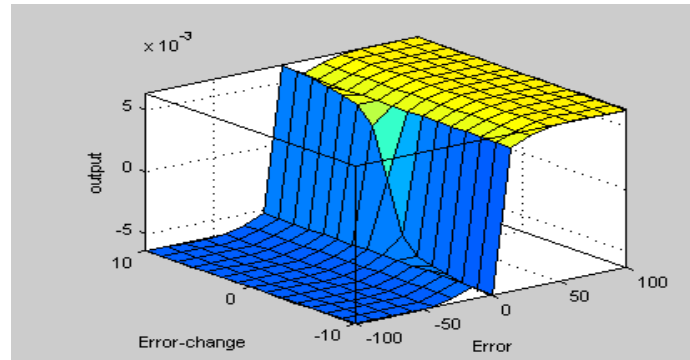


Fig 11: Surface View of Rules of FLC.

Fig.11 shows the representation of the typical Rule Surface of fuzzy logic controller. The Surface View of rules are represented as the combinations of the two inputs error and change in error for a function of output.

Five rules are used for obtaining fuzzy controlled output. They are:

- 1) If (error is negative) then (output is decrease)
- 2) If (error is zero) and (output is negative) then (output is decrease)
- 3) If (error is zero) and (output is zero) then (output is no-change)
- 4) If (error is zero) and (output is positive) then (output is increases)
- 5) If (error is positive) then (output is increases)

VI. SIMULINK MODEL

To verify the practicability and validity of the KY and Buck-Boost converter. MATLAB/ Simulink software is applied for the simulation of the converter with both the controllers (PI and FUZZY). The proposed topology, as shown in Fig1. Input voltage $V_{dc}= 12V$, Output voltage $V_0=72V$. Component values are selected is verified via MATLAB simulation, Coupled inductor $n=N_p : N_s = 1:3$, $L_m=148.7\mu H$, $C_1 = 470\mu F$, $C_2= 100\mu F$, $L_0 = 188 \mu H$ $C_0 = 470\mu F$, resonance inductor $L_r = 10\mu H$ and resonance capacitor $C_r = 10nf$.

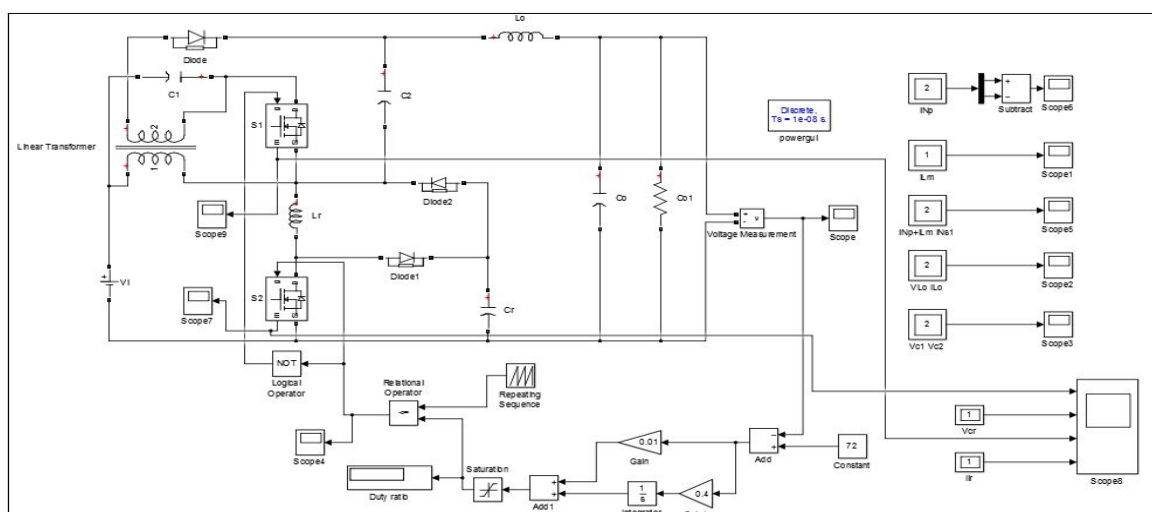


Fig 12:PI controller based on Simulink model

Fig.12 shows the simulink model of the proposed converter using PI controller

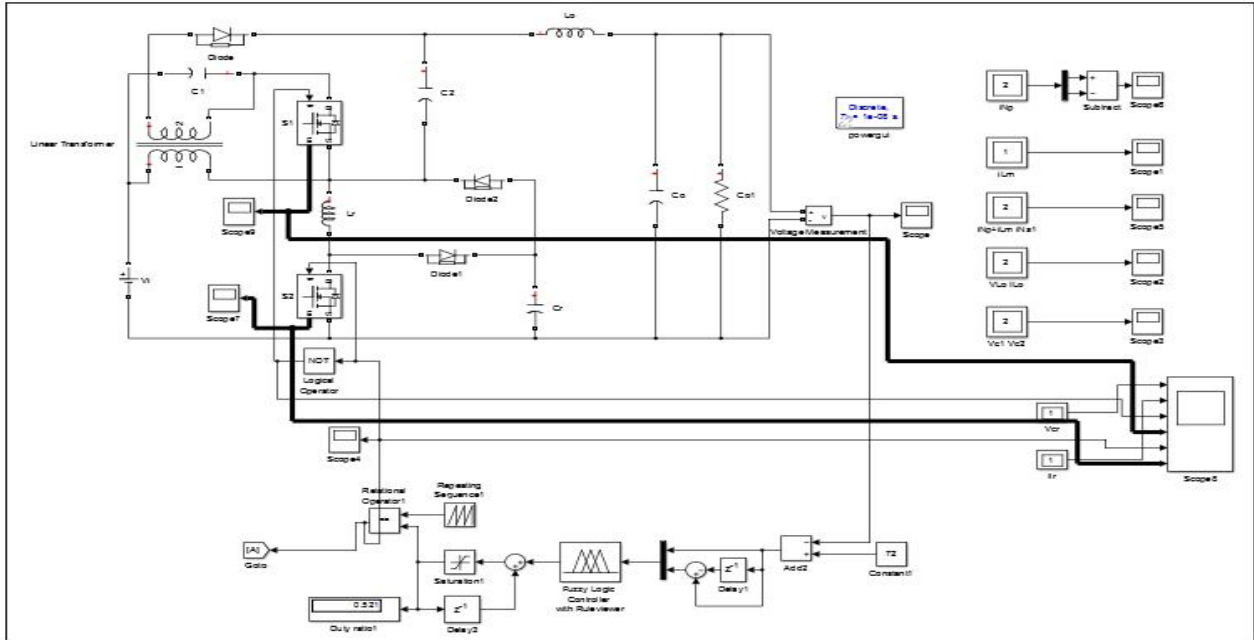


Fig13: Fuzzy controller based on Simulink model

Fig.13 shows the simulink model of the proposed converter using FUZZY logic controller

VII. RESULT AND DISCUSSION

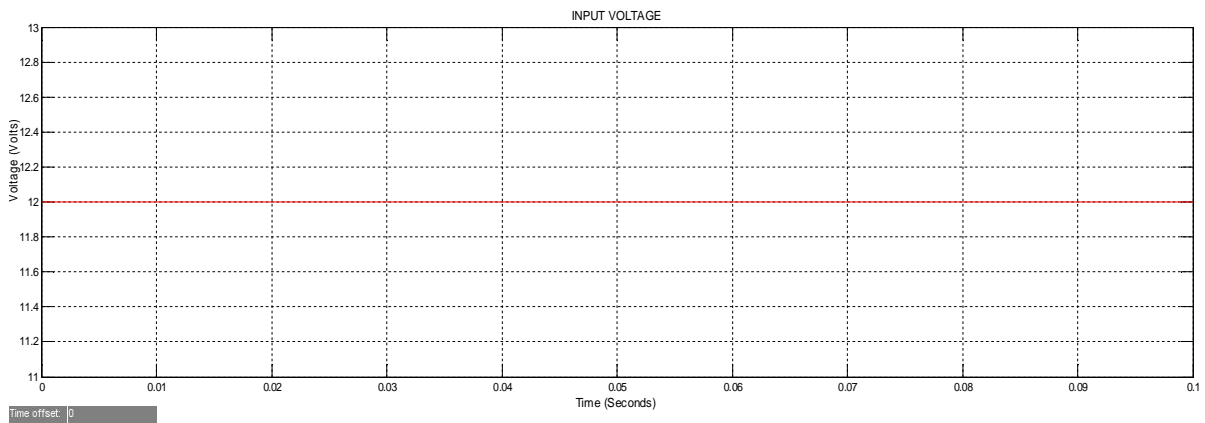


Fig14: Input voltage 12V

12V DC is given to the input of the converter is shown in fig.14

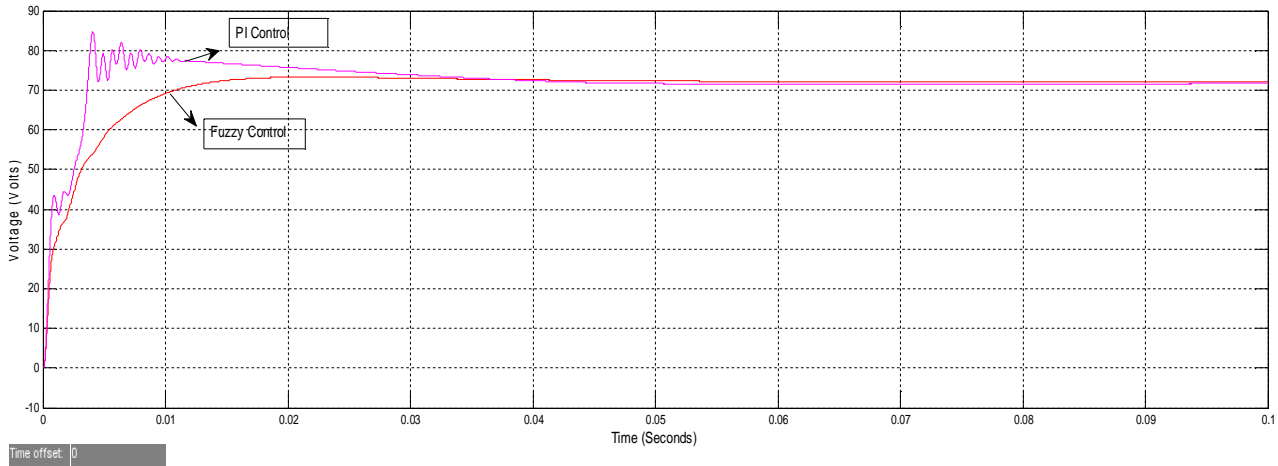


Fig 15: Output voltage waveform of the converter using FLC and PI Controller

The fig.15 shows the output voltage obtained from converter with FLC and PI. Output from FLC gives better performance when compared to converter with PIC. Output from the fuzzy controller will have reduction in settling time, reduction in output voltage overshoot and ripples, however output from PI will have a vice versa result.

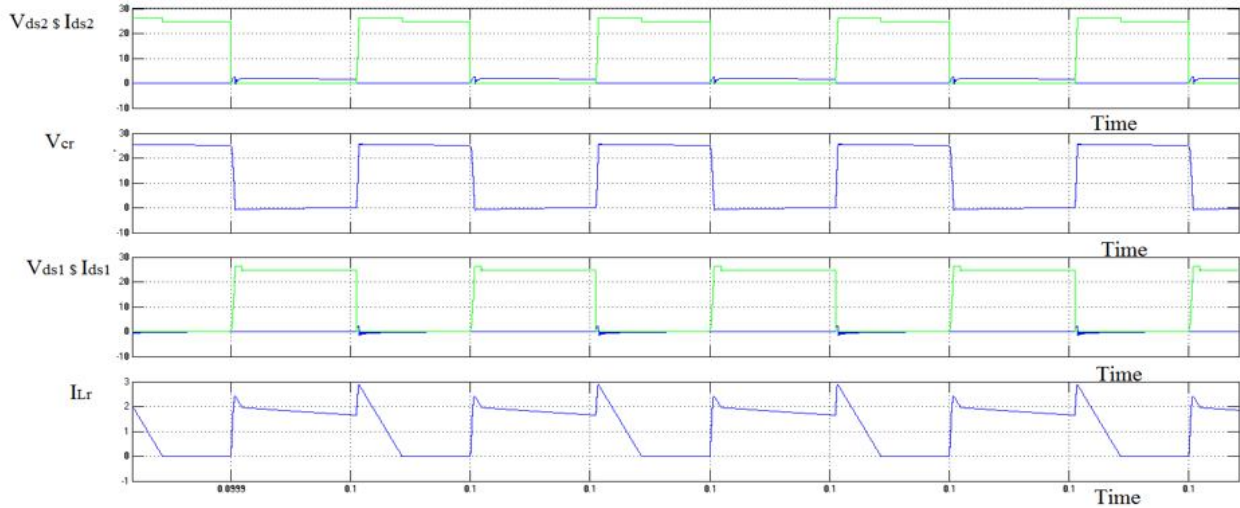


Fig 16 :(1) voltage and current across S_1 (2) Voltage across V_{Cr} (3) Voltage and current across S_2 (4) current flows through I_{Lr}

Voltage and current across switch S_1 is represented as V_{ds1} and I_{ds1} respectively. Similarly voltage and current across switch S_2 is represented as V_{ds2} and I_{ds2} respectively. Zero current turn on and zero voltage turn off is obtained for both switches. Figure 16 (3) and (1) shows the voltage and current across switch S_1 and switch S_2 respectively. Fig 16(2) shows the voltage across V_{Cr} and fig.16(4) shows the current through the resonant inductor. Switch S_1 is turned on first. The current across switch S_1 increases slowly due to the presence of resonance inductor. This will lead to zero current turn on in S_1 . Simultaneously, voltage across switch S_2 increases gradually. i.e., the resonance capacitor is charging gradually and the voltage will come across switch S_2 . Hence the voltage is zero when S_2 is turned off which results in zero voltage switching when switch S_2 is turned on, the current will increase slowly due to the presence of a series inductor which leads to zero current turn on. During this period, zero voltage turn off will happen in switch S_1 .



International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 9, September 2015

VIII.CONCLUSION

Implement a fuzzy logic control for a step-up dc–dc converter by combining the coupled inductor and the switched capacitor with soft switching technic is simulated. A high step-up voltage gain is achieved. The corresponding voltage gain is higher than that of the existing step-up converter combining KY and buck-boost converters. As the output voltage of the converter is controlled with FLC has minimum overshoot, ripple and produces a constant output current which shows better performance when compared to the converter with PI controller. Additionally, the switch voltage stress is reduced by soft switching technic. Furthermore, the proposed converter has no floating output, and it has one output inductor; hence, the output current is nonpulsating. Moreover, the structure of the proposed converter is quite simple and very suitable for communication system and photo-voltaic applications.

REFERENCES

- [1] Y. Deng, Q. Rong, Y. Zhao, J. Shi, and X. He, “Single switch high step-up converters with built-in transformer multiplier cell”, IEEE Trans. Power Electron., vol. 27, no. 8, pp. 3557–3567, Aug. 2012.
- [2] W. Li, W. Li, X. He, D. Xu, and B. Wu, “General derivation law of nonisolated high-step-up interleaved converters with built-in transformer”, IEEE Trans. Ind. Electron., vol. 59, no. 3, pp. 1650–1661, Mar. 2012.
- [3] Y. Hsieh, J. Chen, T. Liang, and L. Yang, “Novel high step-up dc–dc converter for distributed generation system”, IEEE Trans. Ind. Electron., vol. 60, no. 4, pp. 1473–1482, Apr. 2013
- [4] F. L. Luo, “Analysis of super-lift Luo-converters with capacitor voltage drop”, in Proc. IEEE ICIEA, 2008, pp. 417–422.
- [5] K. I. Hwu, Member, IEEE, and W. Z. Jiang, “Voltage Gain Enhancement for a Step-Up Converter Constructed by KY and Buck-Boost Converters”, IEEE Trans On Industrial Electronics, vol. 61, no. 4, April 2014
- [6] K. I. Hwu and Y. T. Yau, “Soft switching of KY converter”, in Proc. IEEE APEC Conf., 2008, pp. 1477–1482
- [7] “Fuzzy Logic Controller”, Control-system-principles.co.uk.