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Comparison between Solar PV Panel Based On MPPT P&O Algorithm and Fuzzy Logic Control

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ABSTRACT: In this paper there is a comparison between power output of solar PV which is based on MPPT P&O algorithm and Fuzzy logic control. Output power of solar PV system is tracked through conventional P&O algorithm and maintains desired output power level. In this system boost converter is used to maintain the output voltage of solar PV system to the desired voltage level. Fuzzy logic control is used in place of conventional MPPT P&O algorithm to track the solar PV output power. The main aim of this project is to show the comparison of conventional MPPT P&O algorithm and the Fuzzy logic control.

KEYWORD: Mathematical modeling of solar PV module, Introduction of MPPT, MPPT algorithm, Fuzzy logic controller.

I. INTRODUCTION

One of the biggest concerns in the power sector is the increasing power demand day by day but the absence of enough resources to meet the demand of power using the conventional sources of energy. Demand has increased for the energy of renewable sources to be utilized with conventional systems to achieve the energy demand. Wind energy and solar energy are the main energy sources which are utilized in this way. Continuously using of fossil fuels caused the reducing of fossil fuel deposit and affected the environment. Depletion of biosphere is also happen due to this.

Solar energy is available in large amount which made it possible to utilize it and harvest it. Solar energy is depends on the presence of a grid and is also act as grid connecting unit. Thus it may be used in rural areas where the presences of grids are very low. Another advantage of solar energy is the portable operation.

For tackle the present energy crisis it is to develop an effective manner in which there is an extraction of power from incoming solar radiation. The mechanisms of power conversion are reduced in size in the past few years. Development of power electronics and material science are very useful because it helped engineers to come up to withstand demand of high power. Increasing of power density is one of the big disadvantages of these systems. But they can act as a generation source of prime power in competitive markets because of low efficiency and high production of these systems.

The newest mechanisms of power control is called the Maximum Power Point Tracking (MPPT) algorithms which lead the improvement in the efficiency of operation of the modules of solar and so it is also effective in the renewable energy sources utilization.



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II. NOMENCLATURE

In a PV module,

Output voltage is V_{pv}

Output current is I_{pv}

Reference temperature, $T_r = 298$ K

Module operating temperature, T (Kelvin)

Light generated current is I_{ph} .

Module saturation current is I_o .

An ideality factor, $A = 1.6$

Boltzmann constant, $k = 1.3805 \times 10^{-23}$ J/K

Electron charge, $q = 1.6 \times 10^{-19}$ C

Series resistance is R_s .

Short-circuit current is I_{scr} .

The Co-efficient of short-circuit current temperature is K_i .

$I_{scr} = 0.0017A / o_c$

λ Is illumination (W/m²) = 1000W/m²

The silicon band gap is $E_{go} = 1.1$ eV

Number of cells which is connected in series is denoted by N_s .

Number of cells which is connected in parallel is denoted by N_p .

III. MATHEMATICAL MODELING OF SOLAR PV MODULE

A solar cell is fundamentally a p-n junction made-up of thin slices of semiconductor. Direct conversion of electromagnetic radiation to electricity is done in the course of photovoltaic effect. There is a creation of electron-hole pairs in semiconductor when energy of photons is larger than energy band-gap. This situation is occurs when photon are uncovered in sunlight and these electron -holes pairs are proportional to incident irradiation.

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In Figure 3.1. There is an equivalent circuit which shows a PV cell

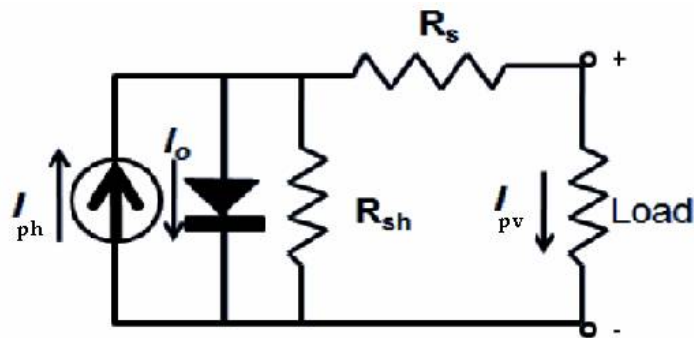


Fig. 3.1 The modeling of PV cell as diode circuit

The photo current of cell is represented by the I_{ph} which is the source of current. R_{sh} is the intrinsic shunt resistance and R_s is the series resistance of cell. Generally the R_{sh} value is very large and R_s value is very small, so they can be neglected for making the analysis simple.

PV modules are the group of larger units of PV cells. For forming the PV arrays they are connected in parallel-series configuration.

In equations (1)- (4) there is a mathematical modeling of photovoltaic panel.

Module photo-current:

$$I_{ph} = [I_{scr} + K_i (T - 298)] * \lambda / 1000 \quad (1)$$

The reverse saturation current of module - I_{rs} :

$$I_{rs} = I_{scr} / [\exp(qV_{oc} / N_s kAT) - 1] \quad (2)$$

The saturation current of module I_0 varies with the temperature of cell, which is specified by

$$I_o = I_{rs} \left[\frac{T}{T_r} \right]^3 \exp \left[\frac{q * E_{g0}}{Bk} \left(\frac{1}{T_r} - \frac{1}{T} \right) \right] \quad (3)$$

The output current of the PV module is

$$I_{PV} = N_p * I_{PV} - N_p * I_o \left[\exp \left\{ \frac{q * (V_{PV} + I_{PV} R_s)}{N_s kAT} \right\} - 1 \right] \quad (4)$$

Where $V_{pv} = V_{oc}$, $N_p = 1$ and $N_s = 36$

IV. INTRODUCTION OF MPPT

There is a power conversion system based on suitable control algorithm which is known as MPPT. It is used in the extracting of maximum power from PV panel. It is independent of the condition of operation (solar irradiation, aging and temperature). The delivered power is maximized by regulating the current which is drawn from panels or the voltage which passes across to it to give way to the operation at or near to the maximum power point (MPP).



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In the literature there are many different techniques of MPPT which have been reported. They are classified as the methods of on-line and off-line. The algorithms which are used in On-line methods are used in the calculating of actual power which is delivered by panels of PV. Then it compares it with previous values and also used in the adjusting of a reference signal which leads the actual MPPT. Off- line methods provide a reference signal which is based on detailed previous knowledge of PV array and parameter measurements like module temperature, solar irradiation level, open circuit and short circuit voltage and current of PV panel's sample.

On line methods contain:

1. Perturbation & Observation algorithm
2. Incremental Conductance algorithm

Off line methods contain:

1. Constant voltage
2. Short- circuit current

V. MPPT ALGORITHM

In MPPT systems there are widely use of P & O algorithms because it has simple structure and simple implementation. In P&O algorithms, the perturbation variable may be the value of reference for terminal voltage of PV panel, output current of PV panel, or duty cycle of MPPT converter. In this algorithm, the voltage is adjusted by the controller from the array in a small amount and measures power. For the next cycle, the direction of the perturbation will carry on in the same direction when the value of power is increasing, otherwise the direction of the perturbation will be reversed. Thus this algorithm is also called hill- climbing algorithm.

5.1 The principle of P & O algorithm :

In P & O algorithms, the perturbation variable may be the value of reference for terminal voltage of PV panel, output current of PV panel, or duty cycle of MPPT converter. In the figure 5.1, when the point of operation is at the left side in MPP then it is identified that output voltage of panel of PV is perturbed with $dp/dv > 0$. Then these algorithms would increase the reference voltage of PV panel. When the point of operation is at the right side in MPP then it is identified that output voltage of panel of PV is perturbed with $dp/dv < 0$. Then these algorithms would decrease the reference voltage of PV panel.

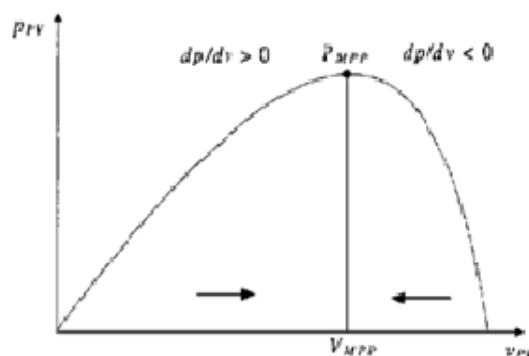


Fig.5.1 operating region on curve of $p_{PV} \times i_{PV}$

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If current is the perturbation variable, after that the perturbation in the output power of PV is proficient by increasing or decreasing of reference current with a small value. The main function in this algorithm is the determination of perturbation.

In fig 5.2, it shows the flow chart of the conventional P&O algorithms. By sensing solar PV voltage and current, power is calculate. In the process power is tracked and maintained power up to maximum power point.

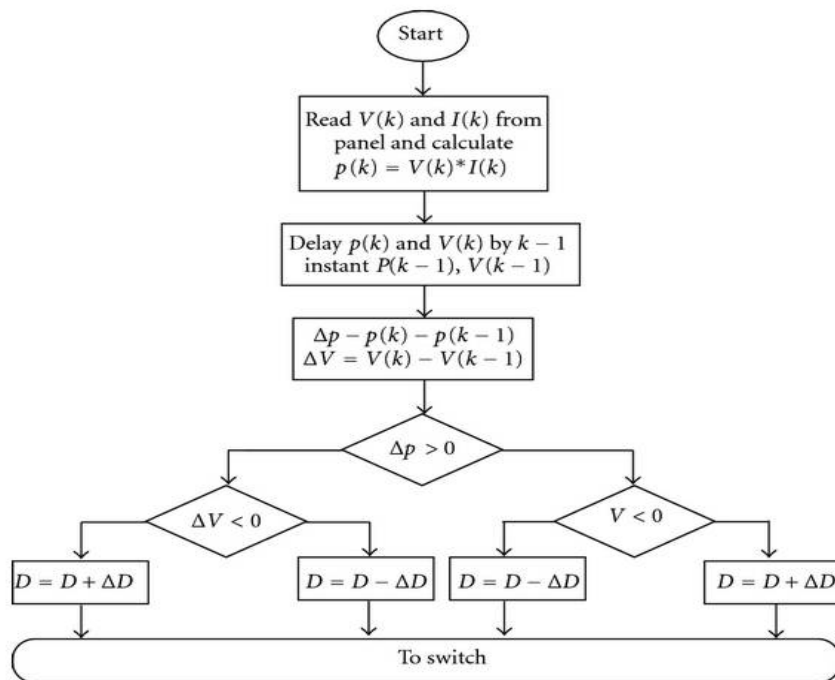


Fig.5.2 Flow chart of P&O algorithms

VI. FUZZY LOGIC CONTROLLER

Most profitable products of fuzzy is rule-based system which receive current information within the loop of feedback from the device since it control and operates the operation of mechanical and other device. There are four blocks in fuzzy logic system which is shown in Fig.3. In the fuzzification block, there is a conversion of crisp input information to fuzzy values which is present in each of the input of fuzzy set. The fuzzy logic operation is determine by decision making logic and the determination of output of each fuzzy is done by IF – THEN rules. Both of them are combined to crispy values and converted to crispy values with defuzzification block.

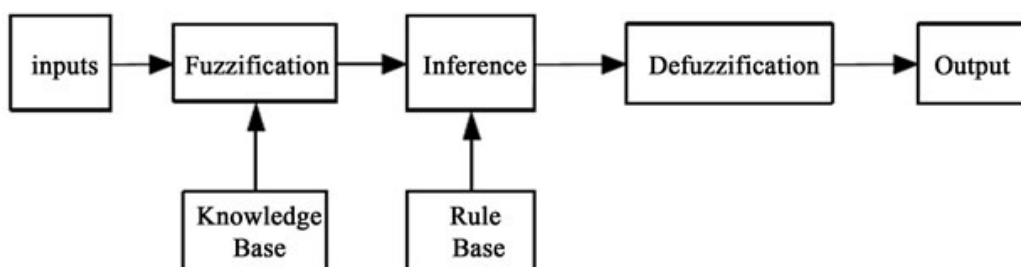


Fig. 6.1 Block Diagram of Fuzzy controller

VII. RESULT AND DISCUSSION

Solar PV System with MPPT P&O Algorithms

In fig 7.1, It shows the block diagram of solar PV system with conventional MPPT P&O algorithms.

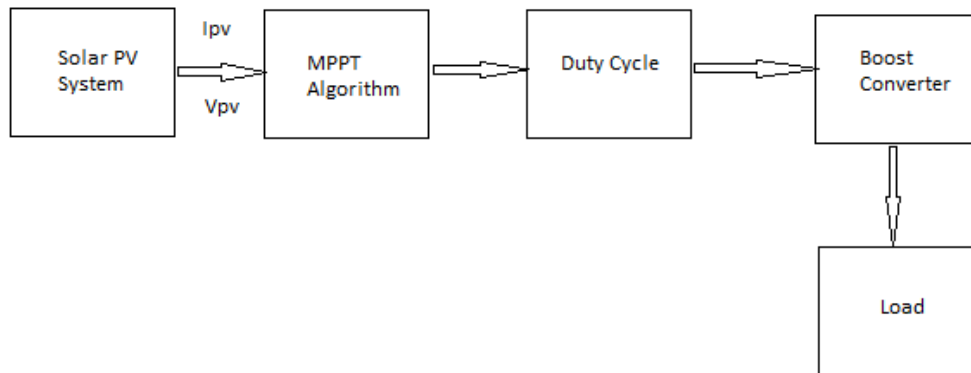


Fig. 7.1 Block Diagram of Solar PV System With MPPT P&O Algorithms

In this system solar radiation from the sun is received by solar PV module and this radiation is converted into electricity. The voltage and current of the solar PV system is sensed by the MPPT P&O algorithm and corresponding duty cycle is generated. With the help of the MPPT the maximum power of the solar system is tracked. Then the corresponding duty cycle is fed to the IGBT of the boost converter and it triggered the IGBT. This boost converter is used to convert output voltage of solar PV system to the desired level. With the help of the simulation the corresponding output is shown and output is shown with the help of the graph.

Simulation Result of Solar PV System with MPPT P&O Algorithms

In fig 7.2 show that the result of simulation of the solar PV system with conventional MPPT P&O algorithms. According to this simulation result there is some time delay for saturating the power curve and also seen that oscillation is increase with increasing time.

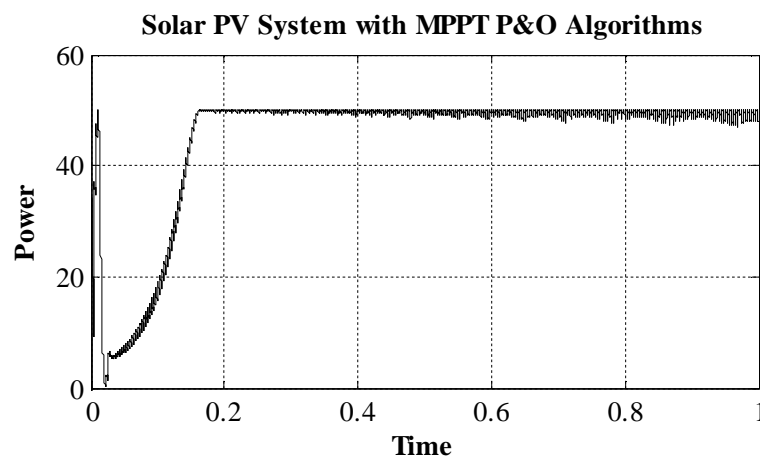


Fig 7.2 Power Curve Solar PV System with P&O Algorithms

Solar PV System with Fuzzy Logic Control

In fig 7.3 show that the block diagram of solar PV system with fuzzy logic controller

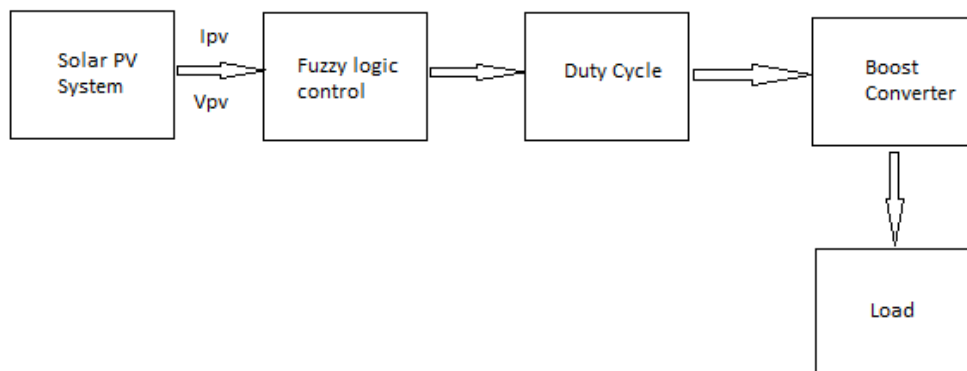


Fig 7.3 Block Diagram of Solar PV System with Fuzzy Logic Control

In this system, the process is same as the as solar PV system conventional MPPT P&O algorithm but the difference is that conventional MPPT P&O algorithm is replaced by fuzzy logic control. With the help of the help of the fuzzy logic control duty cycle is generated and this duty cycle is fed to the IGBT of the boost converter. And this duty cycle is responsible for the triggering of the IGBT of the boost converter. With the help of the boost converter the output voltage of the solar PV system is converted to the desired level of voltage. Through the simulation we get the output result of the simulation with the fuzzy logic control. Through the simulation we find that simulation is faster than conventional MPPT P&O algorithms. Output of the system is shown below.

Simulation Result of Solar PV System with Fuzzy Logic Control

In fig. 7.4 shows that, This graph is resulted from solar PV system with fuzzy logic control. Power curve is saturated in less time than solar PV system with conventional MPPT P&O algorithm. And according to this graph the oscillation present in this graph is less than the conventional MPPT P&O algorithms.

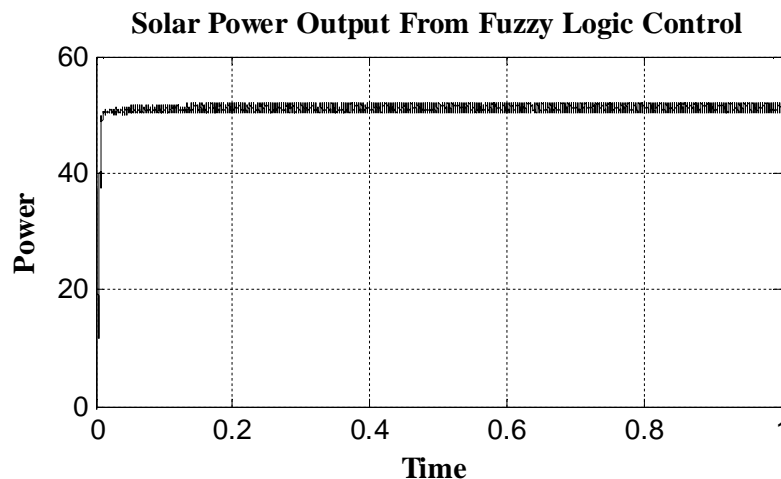


Fig. 7.4 Power curve of solar PV System with Fuzzy Logic Control

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Solar PV System Curves

In fig 7.5 shows that, this graph is shows the I-V characteristic of the solar PV system.

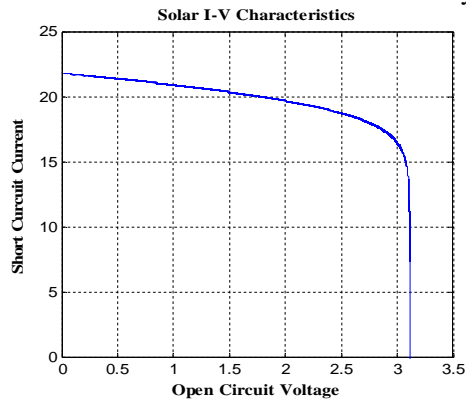


Fig. 7.5 I-V Characteristic of Solar PV System

The MPP (Maximum Power Point) is a point on the I-V curve where the output of maximum power is located. The current and voltage at this point is denoted by I_{mp} and V_{mp} . The maximum power (P_{max}) are also derived from the value of I_{mp} and V_{mp} .

$$P_{max} \text{ (in Watts)} = V_{mp} * I_{mp}$$

The comparison of the performance of solar or PV module, the current versus voltage curve shown its current and voltage output possible combination. The product of current in amperes and the voltage in volts gives the power in the curve at any point.

In fig 7.6 shows that, this graph is shows the P-V characteristic of the solar PV system

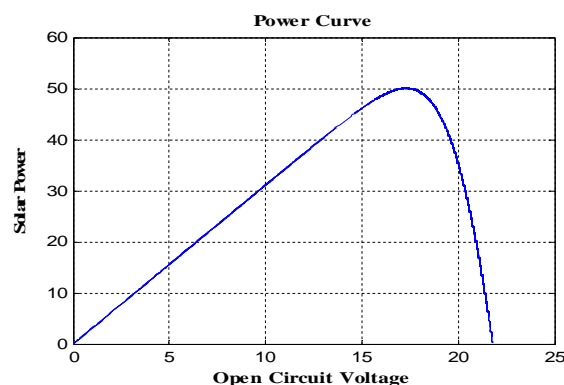


Fig. 7.6 P-V Characteristic of Solar PV System

VIII.CONCLUSION

In this paper, the conclusion of the simulation part shows that the power curve changes with respect to time. In conventional MPPT P&O algorithms the power-time curve is settled after some delay. But with the fuzzy logic control the power-time curve is settled in less delay time in comparison with the conventional MPPT P&O algorithms. And the harmonics generate through the conventional MPPT P&O algorithms is increasing with respect to time as the simulation is running further, but the harmonics generate through the fuzzy logic control is less with respect to conventional MPPT P&O algorithms. So through this conclusion it is clear that the fuzzy logic control is better than conventional MPPT P&O algorithms.



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