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# Implementation of Adaptive Distributed Sparse (ADS) Control Algorithm to Single Stage Grid Connected Solar PV System for DC-AC Conversion

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**ABSTRACT:** This paper deals with the implementation of adaptive distributed sparse (ADS) control algorithm to single stage grid connected -photo voltaic (SSG-PV) system for DC-AC power conversion with expected voltage and frequency levels along with same phase sequence of power grid. The proposed system is used to examine the ADS control algorithm with balanced linear and balanced non-linear loads. Additionally, single stage grid connected photo voltaic (SSGPV) system with ADS control provides active and reactive power balancing, harmonic compensation, VAR generation and quality of power. For extracting maximum power from solar system, the conventional traditional P and O algorithm is used. In the proposed system, single stage means one converter called Voltage source converter (VSC) enough for DC- AC conversions and tracking maximum power transfer from solar system. The performance of the proposed system is simulated on MATLAB/Simulink and achieved total harmonic distortion (THD) of voltage at point of common coupling (PCC) and grid currents within limits according to an IEEE 510 standards.

**KEYWORDS:** Power quality, ADS algorithm, Solar PV system, VSC, MATLAB

## I. INTRODUCTION

In recent time, renewable energy sources have experienced dramatic innovations and improvements in terms of both quality and quantity with increased pressure to overcome environmental problems and economic crisis from increased prices of non-renewable natural resources. Especially, grid-connected solar PV farms have been developed very quickly and the penetration of solar energy in the grid is rapidly increasing. Since solar power is randomly varying and it has to be captured over a wide area for stable and reliable operations. Grid connected solar PV generation has two topologies – single-stage (only one converter between grid and solar PV system) and two-stage (two converters, one is DC-DC converter and second one is VSC, between grid and solar PV system). In this paper, single – stage grid connected photo voltaic (SSG-PV) system is considered and ADS control algorithm implemented on this system for DC-AC power conversion.

In this paper, an ADS control algorithm implemented on SSG-PV system. The P and O control techniques generates a reference DC voltage  $V_{dc}^*$  signal, which is used in ADS control algorithm to extract maximum power from the solar PV system at various irradiation conditions. The target of this paper is to make sure that the control algorithm is able to provide better power DC-AC conversion, load balancing and harmonics compensation.

## II. CONTROL ALGORITHMS OF PROPOSED SYSTEM

Control system of single stage grid connected photo voltaic system consists of two algorithms, one for extracting maximum power transfer from solar PV system, called traditional P and O algorithm and another algorithm is ADS control algorithm for DC-AC power conversion. Both algorithms play a vital role for generating desired gate pulses for VSC operation.



A) Traditional P and O Algorithm:

There are various MPPT techniques explained in [8]. The traditional P and O algorithm is used in this paper for extracting maximum power transfer from solar PV system [9]. Initially, the P and O MPPT needs to take solar array voltage point and solar array current point. From these two points algorithms generates reference DC link voltage  $V_{dc}^*$ .

B) ADS algorithm:

The ADS algorithm schematic diagram shown in figure2. The algorithm needs the following data: solar PV voltage( $V_{PV}$ ) and current( $I_{PV}$ ) ; grid three phase currents ( $i_{sa}, i_{sb}, i_{sc}$ ) ; load currents ( $i_{la}, i_{lb}, i_{lc}$ ) ; voltages ( $v_{ta}, v_{tb}, v_{tc}$ ) at PCC and voltage across the capacitor  $V_{dc}$ .

The voltage amplitude at PCC as,

$$|V_t| = \left( \frac{2}{3} (v_{sa}^2 + v_{sb}^2 + v_{sc}^2) \right)^{1/2} \tag{1}$$

Where, the above voltages are phase voltages which are obtained from measuring line voltages

$$v_{sa} = \frac{1}{3} (v_{sbc} + 2v_{sab}); v_{sb} = \frac{1}{3} (v_{sbc} - v_{sab}); v_{sc} = -\frac{1}{3} (2v_{sbc} + v_{sab}) \tag{2}$$

From equation (2), the in-phase unit templates are

$$z_{san} = \frac{v_{sa}}{V_t}; z_{sbn} = \frac{v_{sb}}{V_t}; z_{scn} = \frac{v_{sc}}{V_t} \tag{3}$$

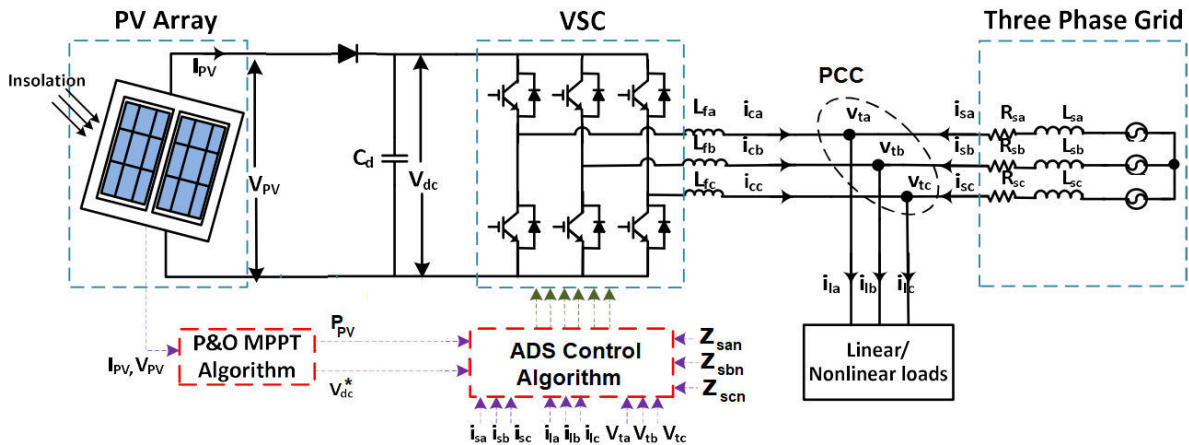


Figure 1: Block diagram of SSG-PV system

In this control system, a simple network considered with ‘n’ node technique. The main objective is to calculate unknown space vector  $A_{usa}^0$ .

The ‘n’ node adaptive technique as shown in figure3. In this, every node m, collaborate with neighbour nodes. In this technique, node n connects to its neighbour estimations  $A_{usan}(m)$ , this estimation is

$$\sigma_{san}(m) = \sum_{l \in S_n} \lambda_{ln} A_{ulin} \tag{4}$$



The error signal is

$$e_{san}(m) = i_{la}(m) - \sigma_{san}(m)^T z_{san}(m) \tag{5}$$

Phase ‘a’ load current estimated as

$$A_{usan}(m+1) = \sigma_{san}(m) + \frac{z_{xa} e_{sa}^3(m) z_{san}(m)}{\|z_{san}(m)\|_2^2 (\|z_{san}(m)\|_2^2 + e_{sa}^2(m))} - \frac{z_{xa}}{\|z_{san}(m)\|_2^2 (\|z_{san}(m)\|_2^2 + e_{sa}^2(m))} \times \xi_{xa} \times \frac{\partial \|\sigma_{san}(m)\|}{\partial \sigma_{san}(m)} \tag{6}$$

Similarly, on phase ‘b’ load current estimated as

$$A_{usbn}(m+1) = \sigma_{sbn}(m) + \frac{z_{xb} e_{sb}^3(m) z_{sbn}(m)}{\|z_{sbn}(m)\|_2^2 (\|z_{sbn}(m)\|_2^2 + e_{sb}^2(m))} - \frac{z_{xb}}{\|z_{sbn}(m)\|_2^2 (\|z_{sbn}(m)\|_2^2 + e_{sb}^2(m))} \times \xi_{xb} \times \frac{\partial \|\sigma_{sbn}(m)\|}{\partial \sigma_{sbn}(m)} \tag{7}$$

Similarly, on phase ‘c’ load current estimated as

$$A_{uscn}(m+1) = \sigma_{scn}(m) + \frac{z_{xc} e_{sc}^3(m) z_{scn}(m)}{\|z_{scn}(m)\|_2^2 (\|z_{scn}(m)\|_2^2 + e_{sc}^2(m))} - \frac{z_{xc}}{\|z_{scn}(m)\|_2^2 (\|z_{scn}(m)\|_2^2 + e_{sc}^2(m))} \times \xi_{xc} \times \frac{\partial \|\sigma_{scn}(m)\|}{\partial \sigma_{scn}(m)} \tag{8}$$

A loss factor ( $V_{error\_dc}$ ) obtained by equating estimated DC voltage ( $V_{dc}^*$ ) and actual DC voltage ( $V_{dc}$ ). To control DC voltage, the value  $V_{error\_dc}$  is given to the proportional-Integral controller.

$$V_{error\_dc}(n) = V_{dc}^*(m) - V_{dc}(m) \tag{9}$$

The output of the PI controller is obtained as,

$$A_{loss}(m+1) = A_{loss}(m) + k_p \{V_{error\_dc}(m+1) - V_{error\_dc}(m)\} + k_I V_{error\_dc}(m+1) \tag{10}$$

Power grid real power component is estimated as

$$A_{snet} = A_{lsa} + A_{loss} - A_{xx} \tag{11}$$

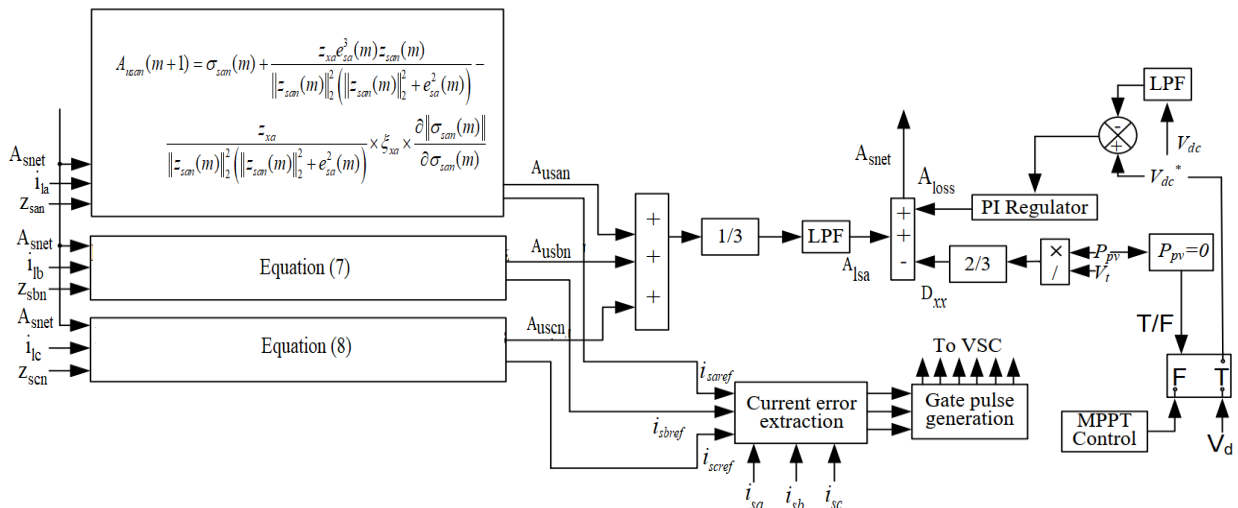


Fig 2: ADS control architecture

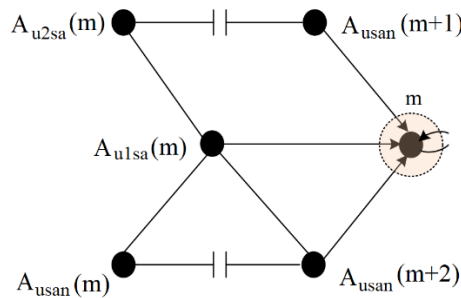


Figure 3: Distributed sparse approach

III. RESULTS AND DISCUSSIONS

The proposed system along with P and O algorithm and ADS control is simulated using MATLAB 2019(a) Sim Power system tool box. The performance of the system was tested under all load conditions (linear and nonlinear).

(i) Performance of proposed System under linear load condition

(a) balanced linear load

Figure4 shows the simulation results of the proposed SSGPV system with DS control under balanced linear load conditions. A three-phase inductive linear load of 16kW, 0.8 lagging power factor placed on SSGPV system. In figure 4 waveforms belongs to three phase grid voltages ( $v_{sa}, v_{sb}, v_{sc}$ ) in volts; three phase grid currents ( $i_{sa}, i_{sb}, i_{sc}$ ) in amps; three phase VSC output voltages ( $v_{ca}, v_{cb}, v_{cc}$ ) in volts; three phase VSC output currents ( $i_{ca}, i_{cb}, i_{cc}$ ) in amps; solar PV power  $P_{PV}$  in watts; active power ( $P_1$ )in watts and reactive power( $Q_1$ ) in VAR of the load ; three phase load voltages ( $v_{la}, v_{lb}, v_{lc}$ ) in volts; three phase load currents ( $i_{la}, i_{lb}, i_{lc}$ ) in amps ; Solar PV array voltage( $V_{PV}$ )in volts and current ( $I_{PV}$ )in amps; DC voltage ( $V_{DC}$ ) in volts; active power ( $P_{inv}$ ) in watts and reactive power( $Q_{inv}$ ) in VARs of the inverter; active power ( $P_s$ ) in watts and reactive power ( $Q_s$ ) in VARs of the grid; All waveform in figure 4 observed under steady state and liner load conditions. An 16Kw+12Kvar resistive-inductive linear load is connected to the point of common coupling (PCC), the16Kw load demand power balances by grid and solar PV system with 6Kw and 10Kw respectively and 12 Kvar reactive supplies locally by VSC so reactive power generated by grid is Zero. Total harmonic distortion (THD) of voltage at point of common coupling (PCC) and grid currents within limits according to an IEEE 510 standards.

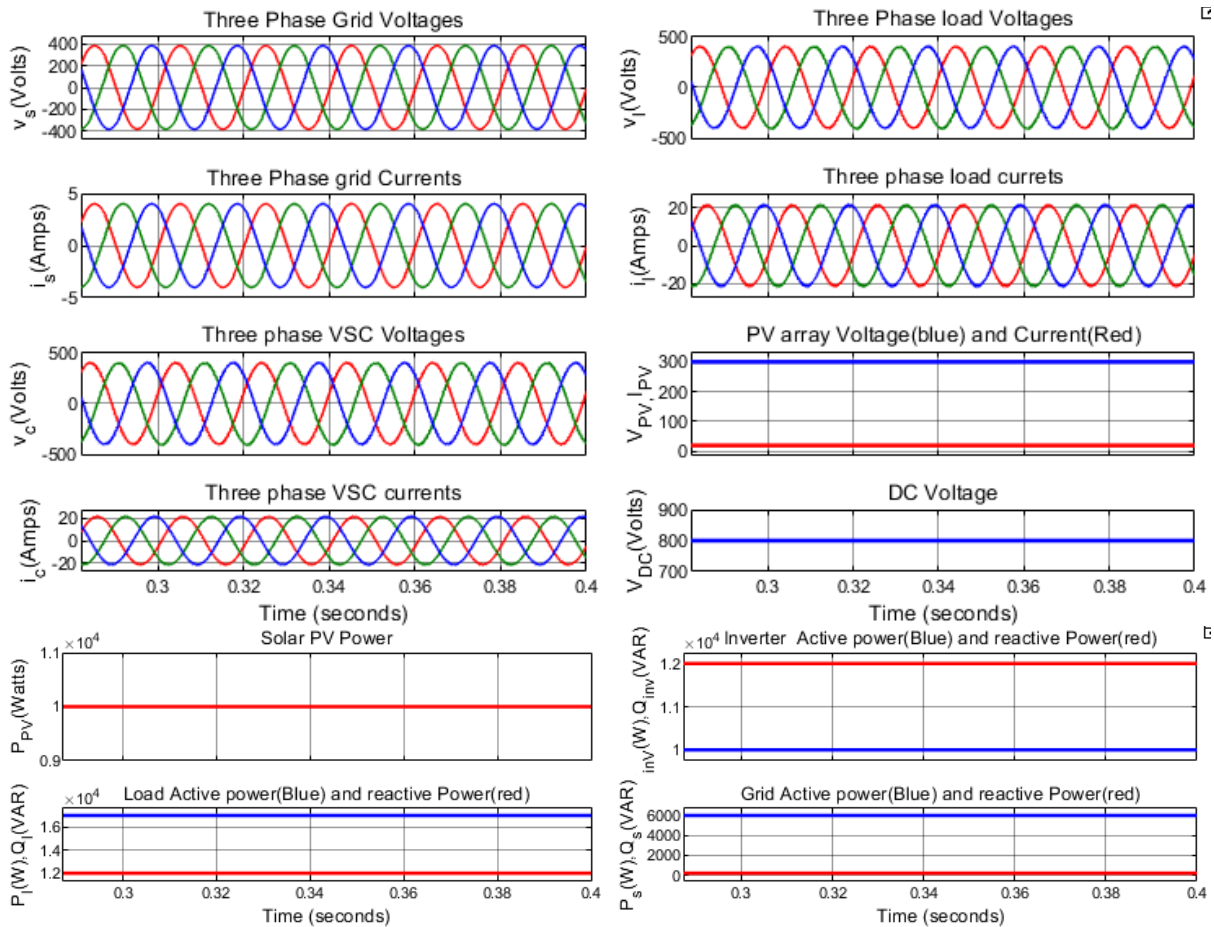


Figure 4: Performance of SSG-PV system under balanced linear load condition

(ii) Performance of proposed System under linear load condition  
 (b) balanced non-linear load

Figure 5 shows the simulation results of the proposed SSGPV system with DS control under balanced non-linear load conditions. A three-phase inductive non-linear load of  $11\Omega$  and  $0.7\text{mH}$  is placed on SSGPV system at  $t=5\text{sec}$ . In figure 5 waveforms belong to three phase grid voltages ( $v_{sa}, v_{sb}, v_{sc}$ ) in volts; three phase grid currents ( $i_{sa}, i_{sb}, i_{sc}$ ) in amps; three phase VSC output currents ( $i_{ca}, i_{cb}, i_{cc}$ ) in amps; three phase load currents ( $i_{la}, i_{lb}, i_{lc}$ ) in amps; DC voltage ( $V_{DC}$ ) in volts; Solar PV array voltage ( $V_{PV}$ ) in volts and current ( $I_{PV}$ ) in amps; solar PV power  $P_{PV}$  in watts; load active power ( $P_l$ ) in watts and grid active power ( $P_s$ ) in Watts. All waveform in figure 5 observed under steady state and non-linear load conditions. A resistive-inductive linear load is connected to the point of common coupling (PCC), the load demand power balances by grid and solar PV system respectively and reactive supplies locally by VSC so reactive power generated by grid is Zero. According to IEEE standards the harmonic content levels on grid currents a voltage within permissible limits and also it was observed that Solar PV system was able to generate power smoothly. So, ADS control algorithm perfectly is suitable for SSGPV system under non-linear balanced load conditions. Total harmonic distortion (THD) of voltage at point of common coupling (PCC) and grid currents within limits according to an IEEE 510 standards.

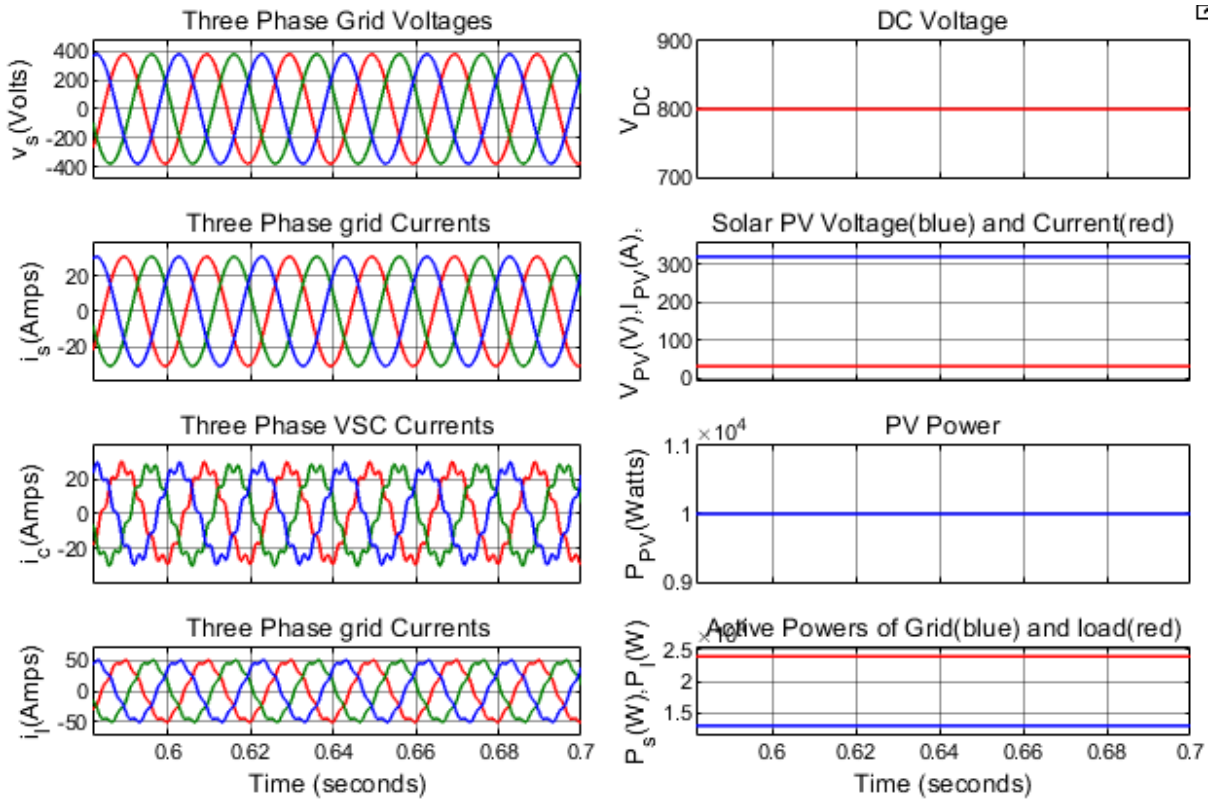


Figure5: Performance of SSGPV system under balanced non-linear load condition

TABLE 1: PERFORMANCE OF THE proposed SYSTEM IN TERMS OF THD

Parameter/load	% THD on Load current	% THD on grid current	% THD on VSC current
Linear load	3.27%	2.43%	1.89%
Non-linear load	23.83%	2.02%	14.21%

TABLE 1: PERFORMANCE OF THE proposed SYSTEM IN TERMS OF THD

Parameter/load	% THD on Load voltage	% THD on grid voltage	% THD on VSC voltage
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#### IV. CONCLUSION

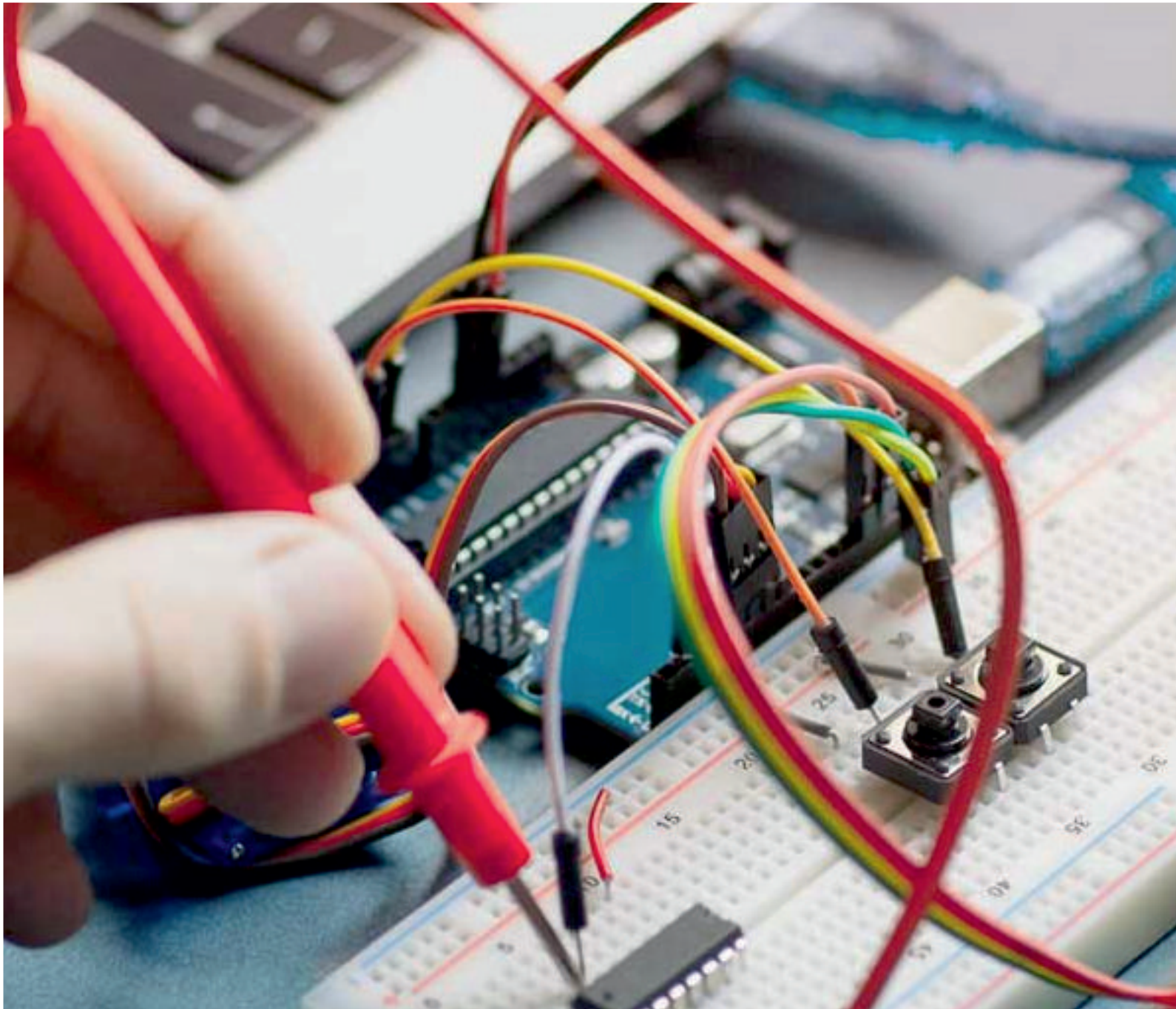
The single stage solar PV system has been integrated to three-phase AC grid using ADS control algorithm for DC-AC power conversion with expected voltage and frequency levels along with same phase sequence of power grid. The SSGPV system supplies real power and reactive power to connected loads and also reduces the several power quality issues like current harmonics distortion, voltage harmonics distortion and load unbalancing under steady state conditions. ADS control with P and O based MPPT has been found easy to implement on proposed SSGPV. The performance of the system has been simulated in MATLAB/SIMULINK environment under balanced linear and nonlinear load conditions.



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