



Improvement of Auto Wiper Controller According to Rain Force

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ABSTRACT: Wiper structure used to recognize precipitation and institute vehicle windshield wipers without driver association. The structure was made to reduce driving redirections and empower drivers to fixate on essential endeavor of driving. The preoccupation wiped out with the change of this system is the manual difference in wipers when driving in precipitation. The couple of minutes that a driver takes their thought off the road to change a handle while driving in poor atmosphere conditions could incite car crash. The structure uses a blend of impedance and piezoelectric sensors to perceive rain and its power. The structure contains a microcontroller that takes in the data signals from the sensors and controls the movement of the windshield wipers in light of those data signals.

KEYWORDS: ADC (analog to digital convertor), LED (light emitting device), Microcontroller, Piezoelectric Sensor, Windshield.

I. INTRODUCTION

In the course of recent decades, the car business has forcefully examined approaches to misuse present day registering and electronic advances in the improvement of security, dependability, and diversion advances. Regardless of this, programmed rain-detecting wiper frameworks are moderately unprecedented in present day vehicles for various reasons. They are regularly excessively costly, too unattractive, or too untrustworthy to be in any way wanted in new autos. Numerous endeavors have been made at building powerful, dependable, and modest rain identification and wiper control framework for vehicles speed and discontinuous interim consequently as indicated by the measure of rain.

To gauge the measure of water as a rule utilize optical sensor. In this sort of sensors utilizes the way that the refraction edge and the measure of impression of the light are diverse when the 2 windshield is wet. Despite the fact that optical sensors are utilized generally they have some drawback. One of burdens is the affectability to outside light. Another issue is happens when auto drive during the evening or experienced passage and even in underground stopping. For this numerous frameworks still actuate the wiper when the auto leaves passages or underground parking garage. Another deficiency, possibly a noteworthy one is that the detecting zone is a moderately little bit of windshield. Subsequently the framework works just with restricted territory. The wiper framework may neglect to enact when there are a few raindrops on the driver's observable pathway, however not on the detecting region. They are regularly excessively costly, too unattractive, or too inconsistent to be in any way wanted in new autos. Mechanized windshield wiper framework is utilized to recognize precipitation and actuate vehicle windshield wipers without driver communication. The framework is produced to relieve driving diversions and enable drivers to center on their essential assignment of driving.

The diversion disposed of with the improvement of this item is the manual change of windshield wipers when driving in precipitation. The couple of moments that a driver takes their consideration off the street to modify a handle while driving in poor climate conditions could possibly prompt auto collisions. The National Highway and Transportation Safety Association reports that twenty-six percent of all car accidents.



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Therefore the discussion has been confined towards automatic windshield wiper which has a lot of advantages over the basic technology that is used normally in today's world. The low-cost solution proposed by the design will most importantly satisfy the safety and performance requirements needed for the driver at a more reasonable price. The windshield wiper system will manage to do this by the performance of an inexpensive grid sensor.

II. SURVEY ON WIPER SYSTEM

Shantanu Dharmadhikari present the automatic wiper system used to detect rainfall and activate automobile windshield wipers without driver interaction. The system was developed to reduce driving distractions and allow drivers to focus on main task of driving. The demonstration is able to simulate the operation of the system as if installed in an automobile. The team was able to successfully complete the project and satisfactorily meet the proposal goal of automating the driver's response to rain within the specified amount of time of 500 milliseconds.

Sonali B. Madankar, Dr. Milind M. Khanapurkar they mainly concentrated on 3 points that was driver's level comfort, overcome from traditional wiper system and also how can technology used to activate the wiper to operate in full automatic mode and detect moisture using CAN technology. It gave a new dimension of comfort and aid to the drivers who work at night and traffic prone areas where they already have to concentrate on brakes and clutch.

The system was used as component in home automation system because it can detect a sudden rain and notify people in the house. According to Jee-Hun Park, Man-Ho Kim Hong-Jun Im Kyung-Chang Lee and Suk Lee the development of vision-based smart windshield wiper system that can automatically adjust its speed and intermittent interval according to the amount of water drops on the windshield. The system employs various image processing algorithms to detect water drops and fuzzy logic to determine the speed and the interval of the wiper.

Jian HU, Gangyan LI, Duanfeng CHU and Jun XU focused on the passenger car windscreen wiper controller and control method based on CAN. They analyzed the traditional control theory of passenger car windscreen wiper. By comparing the correlative signals of passenger car windscreen wiper between traditional control mode and CAN-based control mode, they concluded that it's necessary to apply the restoration signal of windscreen wiper restoration machine as the input signal of passenger car windscreen wiper controller based on CAN.

Vicknesh.C, Aakash.A.E, Dev.M, Dinesh.S, Lisanson.R idea is to construct an automatic wiper using a sensor as a component which was used to sense the raindrops. The low cost automation was reliable and integrated in Economic class cars. Automation with variable frequency were integrated with incumbent wiper system.

III. SYSTEM DESCRIPTION

The framework rain sensor is utilized to recognize the measure of the rain and its force. This gives the flag to the microcontroller. The ADC in the controller distinguishes the network sensor yield and gives the flag to the PIC microcontroller. A PIC16F877A has an in assembled Capture/Compare/PWM (CCP1) module for which the I/O stick is served by RC2.

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The following Fig.1 shows block diagram of working of automatic smart windshield Wiper.

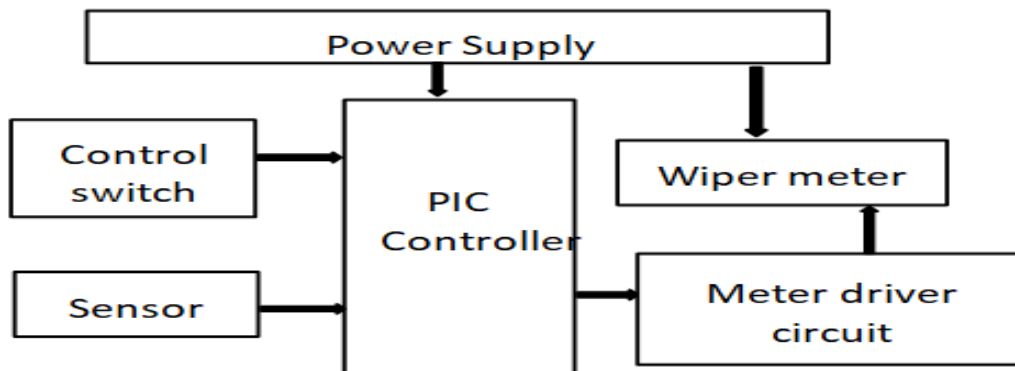


Fig.1 working of automatic smart windshield wiper

A. The product goals

- Detect power of rainfall.
- Activate windshield wipers naturally once rainfall is identified.
- Adverse impacts of incidental and ecological elements.
- Meet or surpass the reaction time of the driver.
- Make versatile to all vehicles.
- Develop high dependability (under five percent power identification mistakes).
- Create easily of establishment.

B. ADVANTAGES

- The cost is lower.
- High affectability.
- High mechanical firmness.
- Broad recurrence runs. Exceptional linearity.
- Excellent repeatability.
- Unidirectional affectability. □
- Small size.

C. TECHNICAL SPECIFICATION

The automated windshield wiper system Consists of the following:

- Sensors that detect rain and its intensity.
- A microcontroller that outputs a control signal to the motor control circuitry.
- Signal-conditioning circuitry to interface with all the components in system.

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Table 1: Technical Specification

Characteristics	Specifications
False Rain Detection Rate	Less than 5 %
Sensors Operational Temperature	-40 to 84°C
Voltage Requirement	12- 5 Volts DC
System Response Time	Less than 500 ms from rain contact
Impedance Sensor Surface Size	<= 4 cmxcm
Seamless Integration and adaptation	Adaptable to all vehicles and tunable sensitivity

IV. STRUCTURE OF VISION-BASED SMART WIPER SYSTEM

As a rule, the detecting region of an optical wiper framework is little; the territory is at most 10mm wide and 30mm long. This influences the entire framework to work on exceptionally restricted data. When it begins to rain, the wiper starts to move simply after a few raindrops fall on to the detecting zone. Also, the wiper may not begin at all when water is sprinkled by different autos on to the territory other than the detecting region.

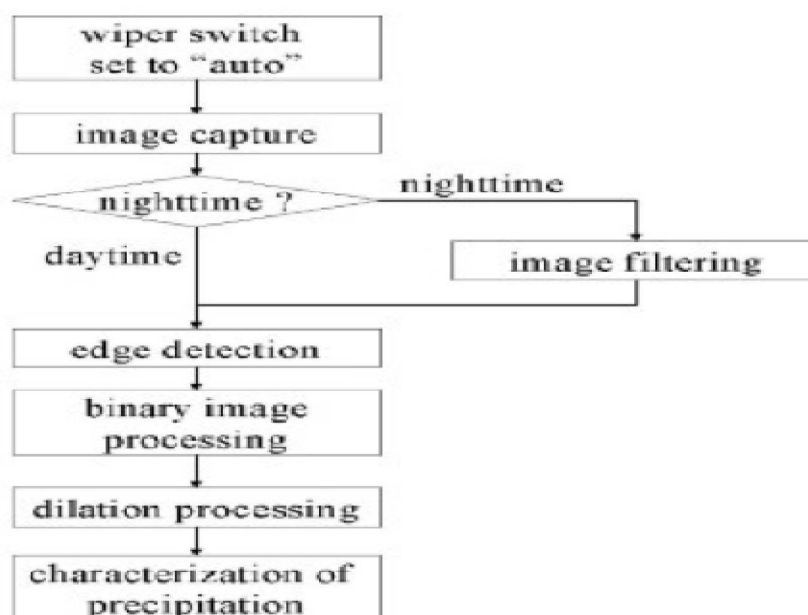


Fig.2 Flowchart of rain sensing algorithm

Keeping in mind the end goal to identify raindrops on the windshield, the calculation finds the limits of raindrops by utilizing an edge location procedure. Among numerous methods, for example, Sobel, Prewitt, Roberts, Laplacian, and Laplacian of Gaussian, the Sobel veil is chosen since its edge location capacity is neither too awful to distinguish raindrops nor too great with the goal that the edge of foundation is recognized. Fig. 3(a) demonstrates a unique picture of rain drops while Fig. 3(b) demonstrates the picture after the Sobel veil is connected. In the figure, we can see that

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the limits of raindrops are clear with no observable edges from the foundation. The picture in Fig. 3(b) still has the limits of the foundation, however not exceptionally obvious, that are spoken to dark pixels. This is on the grounds that the foundation picture is obscured because of the low profundity of field.

Keeping in mind the end goal to evacuate these foundation limits and abbreviate the preparing time, a solitary edge T is connected as appeared the old and new esteems for the pixel, respectively. In this condition, the incentive for T is chosen as 125 after a few trials and errors. Fig.3(c) demonstrates the picture in the wake of threshold where we can see that the dark foundation limits are totally gone. The following stage is to brighten the pixels inside the limit. When it is said to be done, the expansion makes a protest broadened in light of the fact that the task expands the peripheral pixels of the limit. Along these lines, the raindrops will be somewhat bigger and some of raindrops still may have dark pixels inside the limit. In this work, a 3X3 expansion veil, whose pixel esteems are every one of the zeros, is utilized for speedier computational speed. Fig. 3(d) demonstrates the last picture after the widening activity. Looking at Fig. 3(c) with Fig. 3(d), we can confirm that most raindrop limits are loaded with white pixels.

As specified before, the evening time pictures have a tendency to contain more aggravations, for example, road lights, tail lights, and head lights. At the point when the daytime handling calculation is connected to the evening picture, the impact of unsettling influences is as yet staying in the last picture. This show the evening preparing calculation ought to be not quite the same as the daytime calculation. For this reason, we centre on the way that sharp highlights, as a rule, have generally high recurrence components, while obscured highlights have moderately low recurrence components.

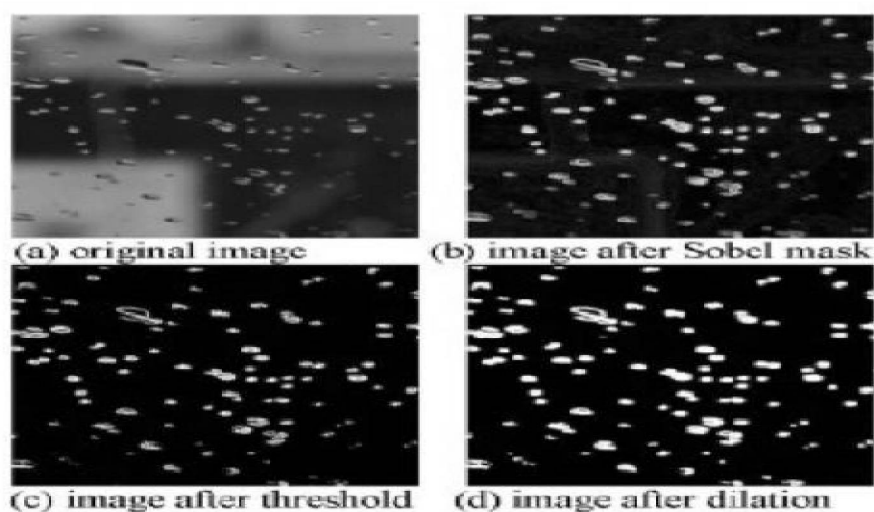


Fig.3 Night time image processing algorithm

That is, the raindrops under the inside LED light are particular and have high recurrence components while the outside light sources are obscured by the low profundity of field and have low recurrence components. In this manner, aggravations by the outer light source can be expelled by taking out low recurrence components from the picture. For expelling low recurrence components, we pick in this work, the slice off recurrence is chosen to be 32, and n is chosen to be 16 by means of a few trials and blunders.

V. CONCLUSION

Programmed wiper control frame work which is enhanced adaptation of irregular wiper framework. This wiper framework lessen lumbering wiper activity and enhance driver's level solace. It will give another measurement of



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solace and help to the drivers who work around evening time and movement inclined zones where they as of now need to focus on brakes and grasp. The expulsion of controlling the wipers amid rain will give them much straightforwardness and enable them to focus on the essential ABC (quickening agent, brake and grip) of driving. Writing overview uncovers that solace and help to the drivers who work around evening time can be gotten by outlining completely programmed method of wiper framework which changes its development as per the rain compel. These sort of wiper controlling framework are obviously better than customary wiper framework and innovation used to enact the wiper distinguishes moister and gives extra solace to the drivers. Wiper control frameworks which work as indicated by rain constrain includes high precision, high affectability, and noncontact estimation. The frameworks are utilized as part in home mechanization framework since it can distinguish a sudden rain and inform individuals in the house.

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