

### International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

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# **Energy Efficient Routing Algorithm**

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**ABSTRACT:** In Wireless Sensor Networks (WSNs), the benefits of exploiting the sink mobility to persist network lifetime have been well recognized. In physical environments, all kinds of obstacles could exit in the sensing field. Therefore, a research challenge is how to efficiently dispatch the mobile sink to find an obstacle-avoiding shortest route. This paper presents an energy-efficient routing mechanism based on the cluster-based method for the mobile sink in WSNs with obstacles. According to the cluster-based method, the nodes selected as cluster heads collect data from their cluster members and transfer the data collected to the mobile sink. The mobile sink starts the data-gathering route periodically from the starting site, then directly collects data from these cluster heads in a single-hop range, and finally returns to the starting site. However, due to the complexity of the scheduling problem in WSNs with obstacles, the conventional algorithms are difficult to resolve. To remedy this issue, we propose an efficient scheduling mechanism based on spanning graphs in this paper. Based on the spanning graph, we present a heuristic algorithm for the mobile sink to find the obstacle-avoiding shortest route. Simulation results verify the effectiveness of our method.

KEYWORDS: Wireless Sensor Networks (WSNs), obstacles, energy-efficient routing, mobile sink, spanning graph.

#### I. INTRODUCTION

Wireless Sensor Networks have been applied in many respects including health monitoring, environmental monitoring, military surveillance, and many others as Internet of Thing. In traditional sensor networks, the sink node is static and the traffic pattern usually follows a many-to one model. Thus sensors near sink node will allow more traffic load and deplete their energy much faster than those far away from sink node, causing hot spot problem, which has severely impact on network connectivity. Compared with traditional network scheme, sink mobility strategy can effectively alleviate the problem so that lengthen network lifetime [1]. The data from static nodes can be collected by mobile nodes in one-hop or multi-hop way. Mobile nodes are used as the mobile sink which moves across the sensing field to collect data. On the one hand, the mobile sink reduces the communication overhead for sensor nodes close to the base station or the sink, which leads to the uniform energy consumption. One the other hand, with the movement of the sink, we can better handle the disconnected and sparse network. Therefore, the network life time can be significantly lengthen by the optimum control of the route of the mobile sink [2].

#### II. METHODOLOGY

In this paper, mobile nodes are used as mobile sinks which move through the sensing field. Note that there is only one mobile sink in our network. At the same time, we assume that there is no hole in the WSN and static sensors are the same in their capabilities. However, in physical environments, the sensing field may be uneven and contain various obstacles. Here, we assume that the mobile sink can't move through these obstacles. Hence, a research challenge is how to find an obstacle-avoiding shortest route for the mobile sink. In this paper, the mobile sink, which is usually mounted on a mobile vehicle equipped with enough energy, collects data from all static nodes by moving across the sensing field. Note

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that the network lifetime is defined as the time interval from sensor nodes start working until the death of all static sensors.

According to the cluster-based algorithm, all sensor nodes in the network are divided into two categories: cluster heads and cluster members. Cluster heads collect data from their cluster members who collect environment information and then forward the data to the sink either directly or via relaying across other cluster heads. Due to movement of the sink, the mobile sink can move nearest the cluster heads and consume less energy. We can balance energy consumption of sensor nodes by using the cluster-based algorithm. Therefore, the network lifetime will be prolonged significantly. To solve the scheduling for the mobile sink, we use the LEACH (low-energy adaptive clustering hierarchy) protocol [3].

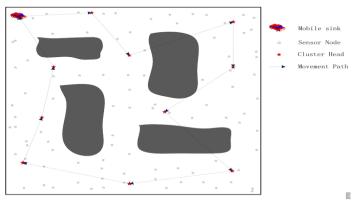


Fig.1. Cluster Partition

From the figure, we assume that the mobile sink can't move across hurdles. To solve the obstacle-avoiding shortest path problem, we present a heuristic obstacle-avoiding procedure.

#### 2.1. Heuristic Obstacle-Avoiding Algorithm:

We present heuristic obstacle avoiding algorithm to find obstacle avoiding shortest path for mobile sink. We use algorithm to build spanning graph of network model. In physical environments, the sensing field may contain hurdles with different shapes and sizes. Due to the irregular shape of obstacles, we can't directly construct the obstacle-avoiding spanning graph for the mobile sink arranging on the basis of the spanning graph algorithm. Therefore, we approach different ways, how to utilize the spanning tree algorithm to find the obstacle free shortest path. The papers [4] use grid-based techniques to analyze and solve problems in WSNs.

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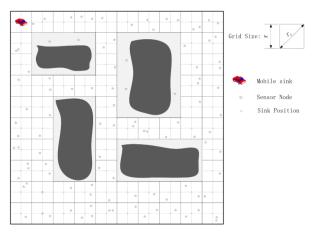


Fig.2. Grid Graph of Sensing Field

Here, we also use grid-based techniques to elucidate the scheduling problem of the mobile sink. The sensing region is distributed into the same size grid cells by means of the grid-based systems. Apparently, edges of obstacles interconnect grid cells and obstacles may occupy part of some grid cells. Once obstacles conquer part of one grid cell, we take on that the grid cell is regarded as obstacles. Therefore, we obtain regularization shape of obstacles that makes it easier for the mobile sink to find an obstacle-avoiding shortest path.

Conferring to the spanning graph of the sensing field in Figure 3, we can finally find the obstacle-avoiding shortest path for the mobile sink.

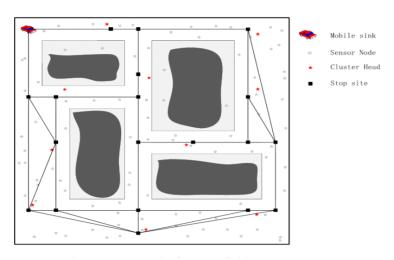


Fig.3. Spanning Graph of Sensing Field

#### III. PERFORMANCE ANALYSIS

In this section, we make use of the heuristic obstacle-avoiding algorithm to conduct numerous experiments in the

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sensing field with obstacles. According to the network lifetime and the movement path of mobile sink, we present investigational results of the algorithm which are given below.

Table.1: System Parameters

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PARAMETERS	VALUES
Grid Size	10m
Dimension of sensing field	10m*10m
Initial Energy	0.4J
Transmit Amplifier	10 (or)0.0013
Number of nodes	100
Data Aggregation	4nJ/bit/report
Transmitter/Receiver Electronic	s 50nJ/bit

Figure 3, shows the network lifetime comparison between the LEACH algorithm, each grid and cluster based algorithm for obstacle avoiding shortest path.

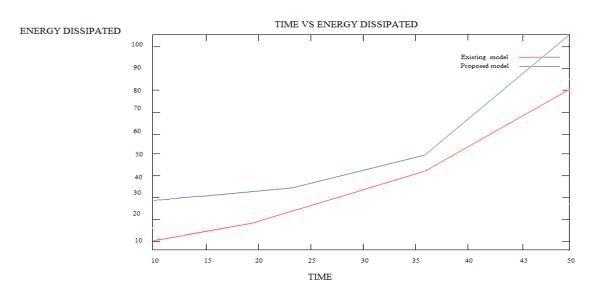


Fig.4.Time Vs Energy Dissipated



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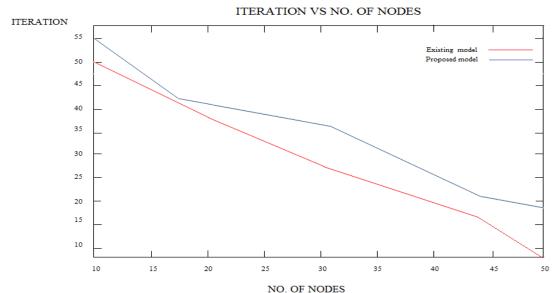
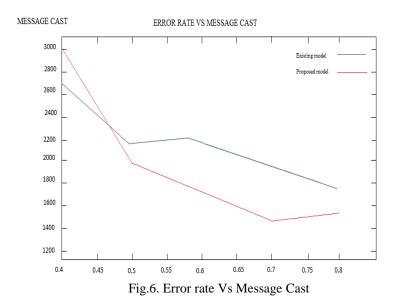


Fig.5. Iteration Vs No.of Nodes



As seen in diagram, we conclude that by changing the dynamic path to static path we increase the network lifetime. This is because by changing to static path. So here, energy consumption is reduced than the previous algorithm.

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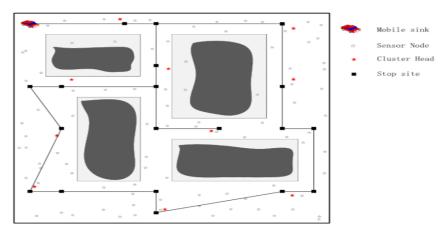


Fig.7. Movement of the mobile sink

The mobile sink, which visits each stop site for collecting data along line segments, begins its movement from the starting site and finally returns to the starting site. Here, we assume that the mobile sink collects data only once each round at the stop site. Taken collectively, our cluster based scheme is more capable than the other schemes. These experiments reveal that we can use heuristic obstacle avoiding algorithm to find an obstacle avoiding shortest way for the mobile sink. In particular, our cluster based scheme better concert.

#### III. CONCLUSION

In this paper, we utilized the mobile sink to extend the network lifetime and cluster based algorithm to consume low energy. At a same time, construct the spanning graph to find the obstacle avoiding shortest path for mobile sink. Finally, found the obstacle avoiding shortest path for extend the network lifetime. Since the Heuristic Obstacle-avoiding Algorithm is used in this paper, to find out the shortest path. The result may change a lot when we used different algorithm. Therefore, how to design a clustering algorithm to make the results optimal is the future work.

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