



NINE-LEVEL Multilevel Voltage Source Inverter with Lower Number of Circuit Devices

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ABSTRACT: An advanced configuration of multilevel inverter is being proposed. There are a number of multilevel inverters available. In this cascaded H-bridge voltage source multilevel inverter is being implemented, it's basically a nine level voltage source inverter which can generate the desired voltages with low number of circuit devices. The size of the proposed device is small compared to other types of multilevel voltage source inverter where nine power semiconductor switches and five dc voltage sources is used including power semiconductor switches and related gate driver circuits. The losses and voltage drops can be reduced more. For step input Multicarrier sinusoidal pulse width modulation (SPWM) technique is implemented. The sinusoidal step output can be observed through simulation and the voltage levels of the output can be calculated. The proposed device finds its application in for industrial motor drives, utility interfaces for renewable energy systems, flexible AC transmission system, high voltage direct current transmission and traction drives systems for controlling the systems.

KEYWORDS : Multilevel Inverter, Voltage drops, Sinusoidal Pulse Width Modulation.

I. INTRODUCTION

A multilevel inverter is a power electronic device which is capable of using multiple lower level DC voltages as an input for providing desired alternating voltage at the output. To generate the AC voltage from DC voltage mostly a three level inverter is used, it creates three different voltages for the load. If V_{DC} is the input given to the three level inverter it produces $+V_{DC}/2, 0$ and $-V_{DC}/2$ as output. These three newly generated voltages are switched usually to build an AC voltage. The ever-increasing demand of power industrial applications, which currently extends from the tens to hundreds of megawatts are traditionally satisfied by large inverters, medium voltage range AC motor drives are example of this fact. Due to high voltage range it is problematic to connect a single power semiconductor switch directly henceforth a new type of power converter has been introduced as a solution. Multilevel converters are used in industrial motor drives, utility interfaces for renewable energy systems, Flexible AC Transmission Systems, High Voltage Direct Current Transmission, and Traction Drives Systems. A number of topologies are available in multilevel inverters namely, Cascade multilevel inverter, Diode clamped inverter, flying capacitor multilevel inverter. The main aim of multilevel inverters is to give high power from medium voltage sources like batteries, super capacitors, solar panel. The DC voltage source implemented in this project is an ideal DC voltage source, four DC supply is used here supplying 10Volts each. The voltage can be modified at any time during the simulation. The main component used in this project is multilevel inverter which converts DC voltage to AC voltage according to the given gate pulse. The gate driver circuit uses step signals to generate gate pulse. The carrier triangular wave produced by using MATLAB function block and the produced wave is compared with sine wave to generate the pulse for gate signal of the semiconductor switches. The amplitude of carrier can be adjusted according to the required duty cycle. The lower input from a controller IC produces a high current drive input for the gate of a high power transistor such as IGBT and POWER MOSFET is been done by the power amplifier. The output voltage can be varied by varying the gate signals given to the IGBT. The obtained AC output voltage can be used for any AC load.

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II. INVERTER TOPOLOGY

An inverter converts the direct current(DC) to alternating current(AC) It usually also increases the voltage, in order to increase the voltage, the current must be decreased, for this an inverter will use a lot of current on the DC side when only a small amount is being used on the AC side. There are a number of modulation techniques namely sinusoidal pulse width modulation, selective harmonic elimination and space vector modulation. The most promising and the latest of such a topology for high power applications is the Modular Multilevel Converter. The main aim of this master thesis project is to deeply investigate and evaluate one of them, based on a carrier phase shifted PWM technique. The four different control topologies used here has three loops of control namely, Averaging Control based on the currents inside the converter, Individual Balancing Control based on the output current and capacitors voltages, and Arm Balancing Control based on the voltage difference between the arms of the converter. Here a switching frequency that meets the two required criteria: low enough to maintain cost feasibility and high enough to reach a harmonic performance target. Here an additional proposal is been made where an analytic expression for the output voltage spectrum of the converter, which enables prediction of harmonic performance.

1. Diode clamped multilevel inverter : A neutral point clamped inverter is the first invention in multilevel converters, it was initially proposed as a three level inverter. The principle of diode clamping can be extended to any level. The diode clamped inverter focuses more on low frequency applications. Diodes are used here to limit power devices voltage stress. The output voltage distortion is very low due to multiple levels in the output voltages. The dv/dt of switches is low since the switches used to reduce voltage, the switches can operate at a lower switching frequency. The common mode voltages are reduced and the input currents have low distortions in application motor drives.

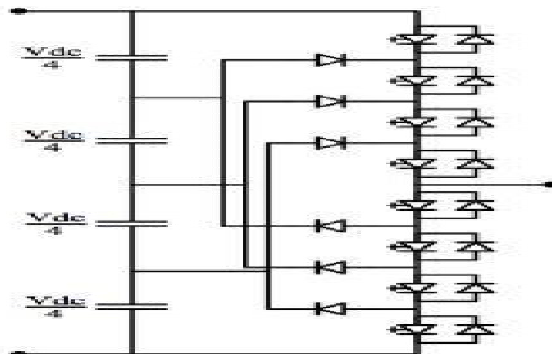


Fig.1 Diode clamped multilevel inverter

2. Flying capacitor multilevel inverter : An alternative for the diode clamped inverter is the capacitor clamped inverter proposed by Maynard and Foch. Structure wise the capacitor clamped inverter is similar to that of the diode clamped converter, with a difference that the diodes used for the clamping are replaced by capacitors. The most common application is static VAR generation.

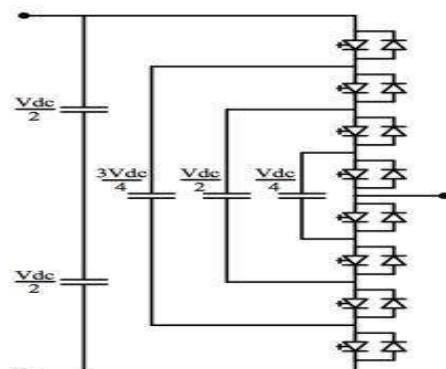


Fig. 2. Flying capacitor multilevel inverter

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3. Cascaded H-Bridge multilevel inverter : The cascaded multilevel inverter is based on the series connection of single leg or double leg (H-bridges) inverters with separate DC sources or capacitors. There are several switching states, the single leg unit has 2 states for each of the two possible currents directions while the double unit has 4 states.

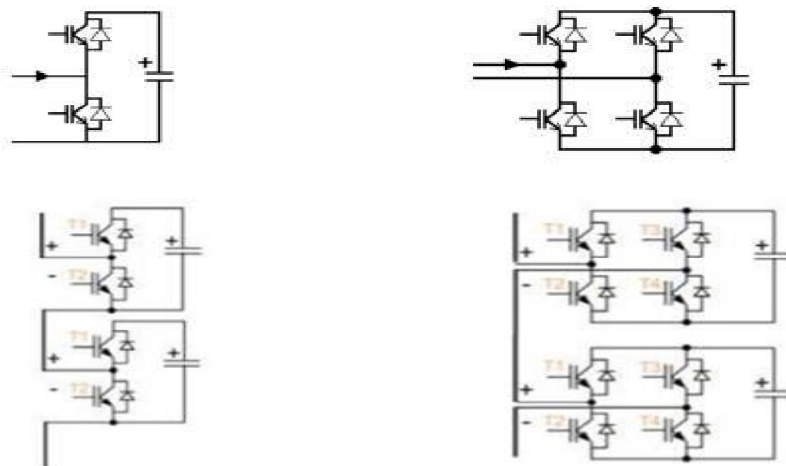


Fig 3. Cascaded H-Bridge multilevel inverter

4. NEW TOPOLOGY FOR MULTILEVEL INVERTER :New topology for multilevel inverter is nine level multilevel inverter and four DC voltage sources. The desired output voltage can be obtained by the gate signal for transistors are given by Multicarrier Sine Pulse Width Modulation technique. The resistive loads are connected in parallel with AC load. The resistance of the load is 20 ohm.

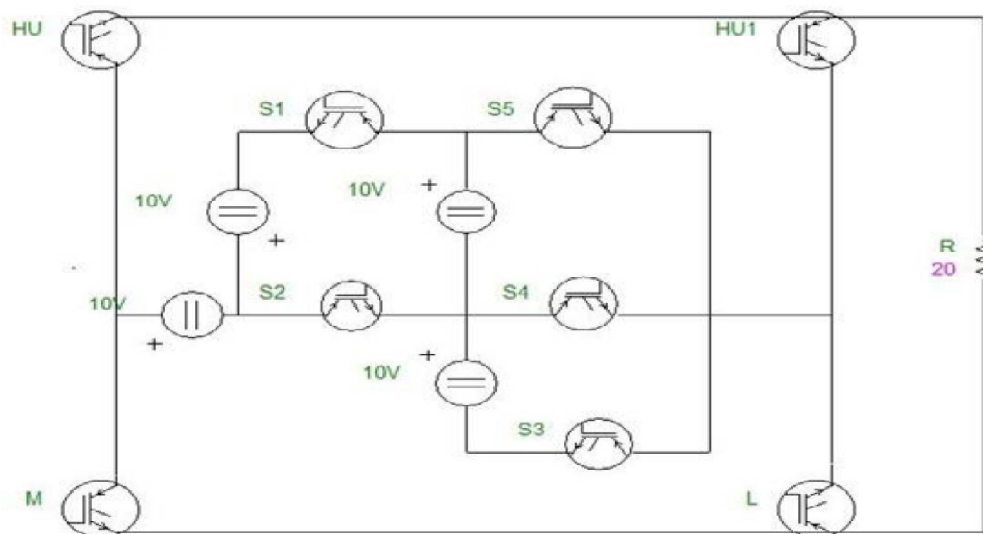


Fig..4 Nine Level Multi Level Inverter



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COMPARISON TABLE :The comparison table compares the existing system and proposed system.

S. NO	EXISTING SYSTEM	PROPOSED SYSTEM
SWITCHES	10	9
PWM	SINE PWM	MULTICARRIER SPWM

Table1. Comparison Table

Here ten switches and sine PWM technique is being used in the existing system, where as in the proposed system uses only nine switches and multicarrier PWM technique is used. The efficiency level can be increased upto 93% whereas in proposed system the efficiency level can be increased upto 96% using lower number of power semiconductor switches. In existing system only one reference signal and carrier signal is used whereas in proposed system several reference signals and only one carrier signal.

III.PWM TECHNIQUE

The single pulse width modulation can be used to convert the reference signal to the square wave signal. There is only one pulse per half cycle and the output rms voltage is changed by varying the width of the pulse. The gating signals are generated by comparing the rectangular control signal amplitude with triangular carrier signal amplitude. The frequency of the control signal determines the fundamental frequency of ac output voltage. The reference signal is obtained to the zero crossing circuits. The amplitude modulation index is defined as $m_a = A_r / A_c$ is also referred as control variable where A_r the amplitude of reference or rectangular signal and A_c is the amplitude of the carrier wave. A_r (reference amplitude) can be varied from 0 to A_c , and the pulse width can be varied from 0 to 100 percent. The transistor works as a switch which is turned on and off by varying the generated gating signals. Adding several pulses in each of the half cycles of output voltage helps to reduce the harmonics. The number of pulses added per half cycle is determined by carrier frequency F_c . The output voltage is controlled by modulation index m_a . This type of modulation is also referred as uniform pulse width modulation. The amplitude of a sine wave is evaluated at the center of the pulse, width of each pulse is varied in proportion to the sine wave amplitude. The distortion factor and lower order harmonics are reduced to minimum. The inverter output frequency and its peak amplitude A_r , is determined by the frequency of reference signal. The modulation index M and V_{rms} output voltage V_o can also be controlled using the same procedure. Classic two level SPWM with triangular carrier and sinusoidal reference waveform is the principle basis for Multilevel Inverter. Two level SPWM and multilevel SPWM differs in number of carriers used, i.e; 'm' level inverter uses 'm-1' carrier. Complementary pair of switches in diode clamped or capacitor-clamped inverter, or particular cell in multi-cell inverter make use of the generated gating signal. Comparison of a low-power reference sine wave with a triangle wave is the simplest way of producing the PWM signal. High switching frequency carrier waves is compared with the reference signal to generate a sinusoidal output wave in multicarrier sine PWM method. The device is turned on and off in the following manner. The reference waveform is compared with carrier signals, if the reference is less than carrier signals then device correspond to carrier is switched off and if it is greater than a carrier signal then switch/device correspond to that carrier is switched on. The widely adopted modulation strategy for MLI (Multilevel inverter) is the above technique. It is similar to that of the sinusoidal PWM strategy except for the fact that several carriers are used. Several triangular carrier signals are compared with one sinusoidal modulating signal in multicarrier PWM.

IV. SIMULATION RESULT AND DISCUSSION

In the fig.9. Pulse generated for semiconductor switches using multicarrier PWM is shown these pulses are given to the corresponding nine semiconductor switches.

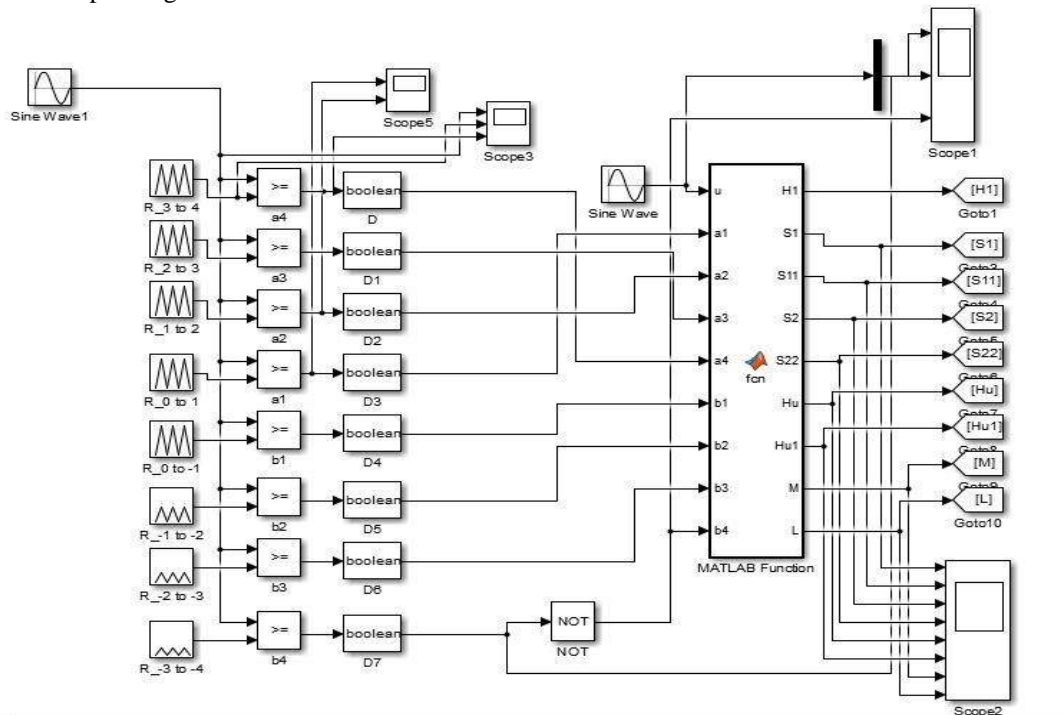


Fig. 5 Generated PWM pulse

SIMULATION CIRCUIT DIAGRAM:

In this fig. 10 has been shown the simulation of the nine level multilevel inverter with reduced number of circuit compenets with R load. Since it is resistive load the output is in phase.

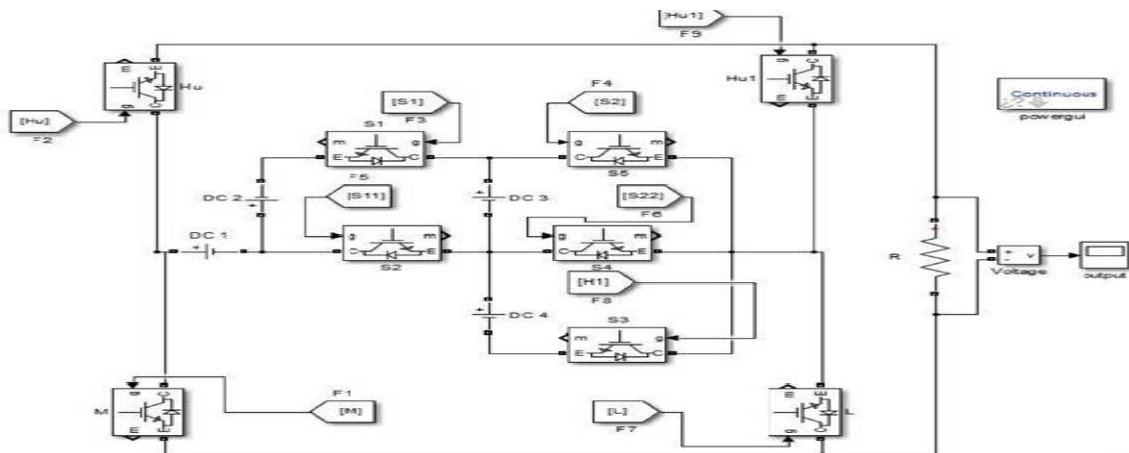


Fig. 6 Simulation circuit diagram

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INPUT and OUTPUT :

In fig.7 DC input is given based on the voltage levels of nine level multilevel inverter. 10V is given for input signal and the output signal may differ. In fig.8 the output of current and voltage level is verified. The voltage level is 40V and the current level is 2amps. The current signal is in the form of sinusoidal signal and the voltage signal is in the form of sinusoidal step output signal.

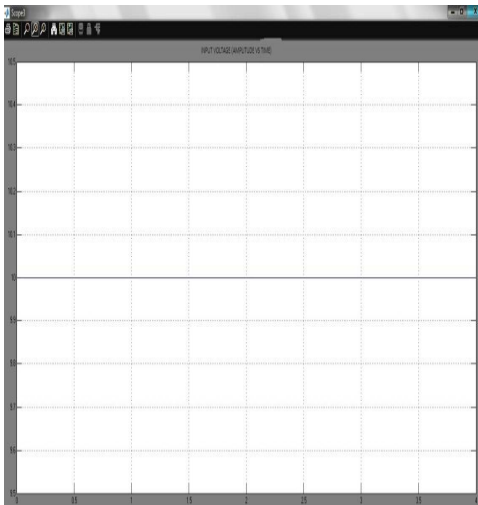


Fig.7 Input voltage

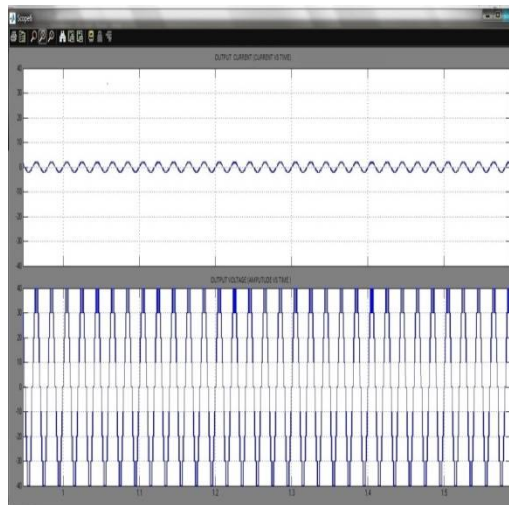


Fig.8 Output waveform

PWM PULSES :

In fig.9 shows the output for multicarrier sinusoidal pulse width modulation and the input for main circuit. There are several step signals based on ON and OFF operations. Each block has several variations based on the input signals. Input signals are given through coding in function block of pwm pulses.

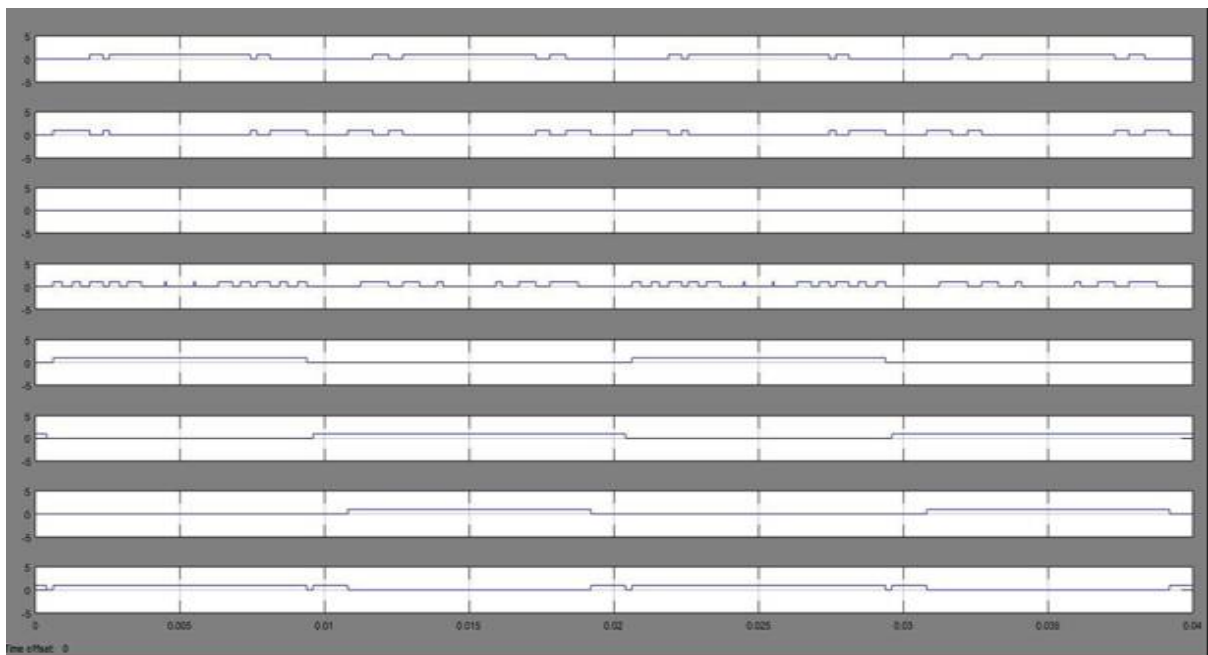


Fig. 9 PWM pulses



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SWITCHING STATES :

DC OUTPUT VOLTAGE	H1	M	S1	S2	Hu	L	S11	S22	Hu1
3VDC	1	0	0	0	1	1	0	1	0
2VDC	1	0	0	0	1	1	1	0	0
1VDC	0	0	0	0	1	1	1	1	0
0	0	0	0	0	0	1	0	0	1
-1VDC	0	1	0	0	0	0	1	1	1
-2VDC	1	1	0	0	0	0	1	0	1
-3VDC	0	1	1	0	0	0	0	1	1

Table .2 Switching states

In Table 2 they are the switching states of semiconductor switches shown in the circuit. When the switch is 1 the device will turn ON and if the switch is 0 then device will turn OFF.

V. CONCLUSION

Proposal of an advanced configuration for symmetrical MVSI (Multilevel Voltage Source Inverter) is taken as the main contribution of this paper. The number of power semiconductor switches and the gate driver circuits has been reduced. Because of the reduced switch count the poer losses have been reduced. The comparative study among the suggested inverter, CHB(Cascaded H-Bridge) and recently proposed converters shows the superiority of the proposed inverter over the mentioned topologies. By reducing the no.of devices there is a substancial reduction in the total costs with a simpler control scheme. The simulation reslts shows the feasibility of the proposed configuration.

VI. FUTURE SCOPE

When compared to other multilevel inverters the proposed inverter, voltage drops and losses can be reduced more. The efficiency level of the inverter can be increased to maximum level through advanced level of heric topology. The voltage can be increased to maximum by using power semiconductor switches. An advanced level of topology can be introduced to make the device more simple and also the voltage losses can be controlled easily. Without using multicarrier spwm technique, the losses and voltage drops can be reduced and also the efficiency can be increased to maximum.

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