



Dynamic Modeling and Control for Solid Oxide Fuel Cell (SOFC)

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ABSTRACT: Fuel cell systems offer clean and efficient energy production and are currently under intensive development by several manufactures for both stationary and mobile applications. It is an electrochemical device that converts the chemical energy of gaseous fuel directly into electricity. This paper deals with the current status and control research on SOFC technologies. Later, the transfer function of the fuel cell is derived by integrating the electrochemical cell reactions. The derived model includes the effect of activation, concentration and ohmic losses on the dynamic performance of SOFC. Within acceptable limits, the effect of Power demand variation on output voltage and real power output are investigated by using different controllers.

KEYWORDS: SOFC, PID, Self-tuning Fuzzy PID Controller

I.INTRODUCTION

Fuel cells convert the chemical energy of gaseous fuel directly into electricity by the electrochemical combination of a fuel with an oxidant. Absolutely harmless water is received as by-product i.e., it is low to zero emissions. Fuel cells feature the potential for high efficiency (35-60%), quiet operation and high reliability due to the limited number of moving parts. They produce power electrochemically by passing a hydrogen-rich gas over an anode and air over a cathode, and introducing an electrolyte in between to enable exchange of ions. The effectiveness of the fuel cell depends on the type of electrolyte employed. Based on the type of electrolyte fuel cells are categorized as Polymer electrolyte fuel cell (PEFC), Alkaline fuel cell (AFC), Phosphoric acid fuel cell (PAFC), Molten carbonate fuel cell (MCFC) and Solid Oxide Fuel Cell (SOFC). Today, PAFCs have been successfully commercialized. The 200 kW PAFC on-site plant, the PC-25, was one of the first to enter the commercial market. Second generation fuel cells (SOFCs and MCFCs) are entered in the market in 2002. PEFCs are still in the development and testing phase [3].

SOFC is a type of fuel cell that appears to be one of the most promising fuel cell systems. Similar to other type of fuel cells, SOFC requires the fuel such as hydrogen, and oxidant reactants such as oxygen or air to electronically react at high temperature and generate electrical energy. Hydrogen is normally used as the fuel since it has high electrochemical activity, but carbon monoxide can be also used as the fuel together with hydrogen. The direct use of a hydrocarbon gas instead of hydrogen or carbon monoxide is also possible when operated as internal reforming.

SOFC has several advantages over other type of fuel cells. It is able to convert carbon monoxide as well as hydrogen, and the high operating temperature allows internal reforming of gaseous fuel and raises rapid kinetics to produce high quality heat for energy conversion. However, there are some disadvantages of this type of fuel cell; i.e, several requirements on its ceramic materials, such as the stability in oxidising and reducing conditions, chemical compatibility with various ceramics employed, thermal expansion compatibility of various components over the large temperature range, and adequate ionic conductivity of the membrane. In a addition, because of the high operating temperature, long waiting times for heat up and cool down cycles are required in order to minimize the structural stresses caused by the expansion and contraction of materials in the cell, which expand and contract at different rates [2].The remainder of this paper is as follows: The dynamic model of solid oxide fuel cell based on transfer function and

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the effect of activation, concentration and ohmic losses on the dynamic performance of SOFC. Control part is discussed in section III & IV and obtained results are analyzed in V and followed by the conclusion and reference.

II. MATHEMATICAL MODELING

The system consists of three primary components, namely, the steam reformer, the fuel cell stack and the combustor. Methane is chosen as the fuel for the system, with a molar flow rate of q_f . The system is presented in Fig(1). The reformer produces a hydrogen rich gas, which is supplied to the anode of the fuel cell. Electrochemical reactions occurring at the anode due to current draw results in a steam rich gas mixture at its exit. A known fraction k of the anode exhaust is recirculated through the reformer into a mixing chamber where fuel is added. The mixing of the two fluid streams and pressurization is achieved in the gas mixer using an ejector or recirculating fuel pump. The steam reforming process occurring in the reformer catalyst bed is an endothermic process. The energy required to sustain the process is supplied from two sources, namely, the combustor exhaust that is passed through the reformer from two sources, namely, the combustor exhaust that is passed through the reformer and the aforementioned recirculated anode flow as shown in Fig. (1). The remaining anode exhaust is mixed with the cathode air, which has a molar flow rate of q_{air} . The tubular construction of each cell causes the air to first enter the cell through the air supply tube and then reverse its direction to enter the cathode chamber. For steam reforming of methane, we consider a packed-bed tubular reformer with nickel-alumina catalyst [11].

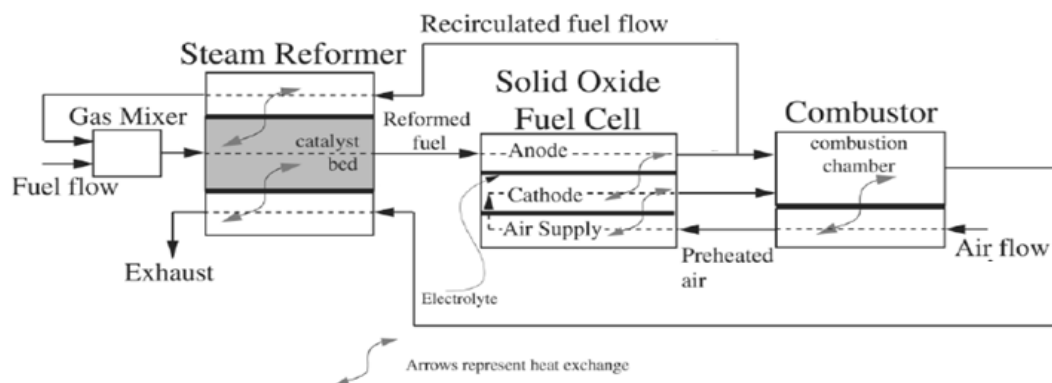
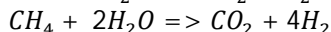
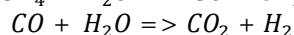
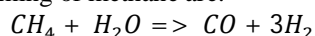


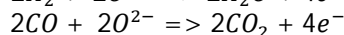
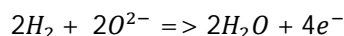
Fig. (1) Schematic diagram of SOFC system.

The three main reactions in steam reforming of methane are:

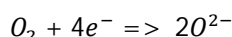


Internal reforming reactions occur in the anode due to high temperatures and the presence of nickel catalyst. The primary electrochemical process is

At Anode:



At Cathode:



The model used in this paper is based on the electrochemical properties (component material balance equations) and Nernst's voltage equation. The temperature is assumed to be stable at all times. The model considers the system in its normal operating conditions; start-up; shut-down operations are far away from the nominal power production and hence are not considered in this paper.

Electrochemical properties



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Assuming perfect gas behavior for hydrogen at the anode channel, we have

$$P_{H_2}V = \eta_{H_2}RT$$

Defining

$$q_{H_2} = \frac{d\eta_{H_2}}{dt}$$

Where the derivative is with respect to time (s), we get

$$\frac{dP_{H_2}}{dt} = \frac{RT}{V}q_{H_2}$$

Splitting the hydrogen molar flow rate q_{H_2} into its three components- the input flow rate, the output flow rate, and the flow rate that takes part in the reaction- we have

$$\frac{dP_{H_2}}{dt} = \frac{RT}{V}(q_{H_2}^{in} - q_{H_2}^{out} - q_{H_2}^r) \quad (1)$$

Similarly, for water vapor at the anode channel,

$$\frac{dP_{H_2O}}{dt} = \frac{RT}{V}(0 - q_{H_2O}^{out} - q_{H_2O}^r) \quad (2)$$

Again, the process of oxygen inflow/ outflow/ reaction at the cathode channel is described by

$$\frac{dP_{O_2}}{dt} = \frac{RT}{V}(q_{O_2}^{in} - q_{O_2}^{out} - q_{O_2}^r) \quad (3)$$

From the basic operation of the SOFC we know that four electrons are consumed for each moles of oxygen and two electrons for each moles of hydrogen. Water, however, is produced at the rate of one moles of every two electrons. From electrochemical properties it follows that

$$q_{H_2}^r = \frac{N_0 I_{fc}}{2F} = 2K_r I_{fc}$$

$$q_{O_2}^r = \frac{N_0 I_{fc}}{4F} = K_r I_{fc}$$

Assuming that the molar flow of a gas through the valve is proportional to its partial pressure inside the channel, we have

$$\frac{q_{H_2}^{out}}{P_{H_2}} = K_{H_2} \text{ and } \frac{q_{H_2O}^{out}}{P_{H_2O}} = K_{H_2O}$$

At the anode, and

$$\frac{q_{O_2}^{out}}{P_{O_2}} = K_{O_2}$$

At the cathode, now, substituting for the output flow rates and reaction flow rates in equations (1) and (2), and taking Laplace transforms, we obtain the following two equations for the anode channel (the transform of $f(t)$ is denoted by $F(S)$):

$$P_{H_2}(S) = \frac{1/K_{H_2}}{1+\tau_{H_2}S} (q_{H_2}^{in} - 2K_r I_{fc}) \quad (4)$$

Similarly

$$P_{H_2O}(S) = \frac{1/K_{H_2O}}{1+\tau_{H_2O}S} (2K_r I_{fc}) \quad (5)$$

$$P_{O_2}(S) = \frac{1/K_{O_2}}{1+\tau_{O_2}S} (q_{O_2}^{in} - K_r I_{fc}) \quad (6)$$

Where

$$\tau_{H_2} = \frac{v}{K_{H_2}RT}, \quad \tau_{H_2O} = \frac{v}{K_{H_2O}RT} \quad \text{and} \quad \tau_{O_2} = \frac{v}{K_{O_2}RT}$$

The inverse transforms of equations (4)-(6) will yield the time domain expressions for the three partial pressures at constant molar flow rate and fuel cell stack current is given below:

$$P_{H_2}(t) = 1/K_{H_2} \left((q_{H_2}^{in} - 2K_r I_{fc}) \left(1 - \exp\left(\frac{-t}{\tau_{H_2}}\right) \right) \right)$$



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$$P_{H_2O}(t) = 1/K_{H_2O} \left((2K_r I_{fc}) \left(1 - \exp \left(\frac{-t}{\tau_{H_2O}} \right) \right) \right)$$

$$P_{O_2}(t) = 1/K_{O_2} \left((q_{O_2}^{in} - K_r I_{fc}) \left(1 - \exp \left(\frac{-t}{\tau_{O_2}} \right) \right) \right)$$

At steady state condition:

$$P_{H_2}(t) = 1/K_{H_2} (q_{H_2}^{in} - 2K_r I_{fc}) \quad (7)$$

$$P_{H_2O}(t) = 1/K_{H_2O} (2K_r I_{fc}) \quad (8)$$

$$P_{O_2}(t) = 1/K_{O_2} (q_{O_2}^{in} - K_r I_{fc}) \quad (9)$$

Output voltage

The open circuit emf E, of a stack of N_0 cells in series is given by Nernst's equation:

$$E = N_0 \left\{ E_0 + \frac{RT}{2F} \ln \left(\frac{P_{H_2} \sqrt{P_{O_2}}}{P_{H_2O}} \right) \right\}$$

The following types of losses (or voltage drops or irreversibility) are generally considered in the literature:

Activation loss: Activation loss caused by the slowness of the electrochemical reactions taking place on the surface of the electrode

$$V_{act} = \frac{RT}{\alpha nF} \ln \frac{i_{den}}{i_{0,den}}$$

Where α is the electron transfer coefficient, n is the number of electrons (per mole) participating in the reaction, i_{den} is the current density, and $i_{0,den}$ the exchange current density.

Concentration loss: Concentration loss (or mass transport loss) that results from the change in concentration of the reactants at the surface of the electrodes as the fuel is used:

$$V_{conc} = \frac{RT}{nF} \ln \left(1 - \frac{i_{den}}{i_{limit,den}} \right)$$

Where n is the number of electrons transferred per mole, i_{den} is the current density, and $i_{limit,den}$ the limiting current density.

Ohmic loss: Ohmic loss due to the electrical resistance of the electrodes and the electrolyte. This resistance, represented by r , depends upon the stack temperature

$$V_{ohmic} = r I_{fc}$$

We obtain the steady-state SOFC stack terminal voltage is as:

$$V_{fc} = E_{nernst} - V_{act} - V_{conc} - V_{ohmic}$$

Fuel utilization is the ratio between the fuel flow that reacts and the input fuel flow.

$$U_f = \frac{q_{H_2}^r}{q_{H_2}^{in}}$$

Where

$$q_{H_2}^r = \frac{N_0 I_{fc}}{2F} = 2K_r I_{fc}$$

The ratio of hydrogen to oxygen flow rate is as:

$$r_{OH} = \frac{q_{H_2}^{in}}{q_{O_2}^{in}}$$

Mathematical modeling of dynamic SOFC is shown in Fig (2).

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III. CONVENTIONAL CONTROLLER

PID (Proportional, Integral and Differential) controller is the most common form of feedback. In PID controller the basic idea is the examination of signals from sensors placed in the system, called feedback signals. PID as one of widely used control approaches has many advantages such as simple control structure, easy design and inexpensive cost etc. The PID controller has been used in different controlled plant. However it cannot get a good control effect when controlled system is nonlinear

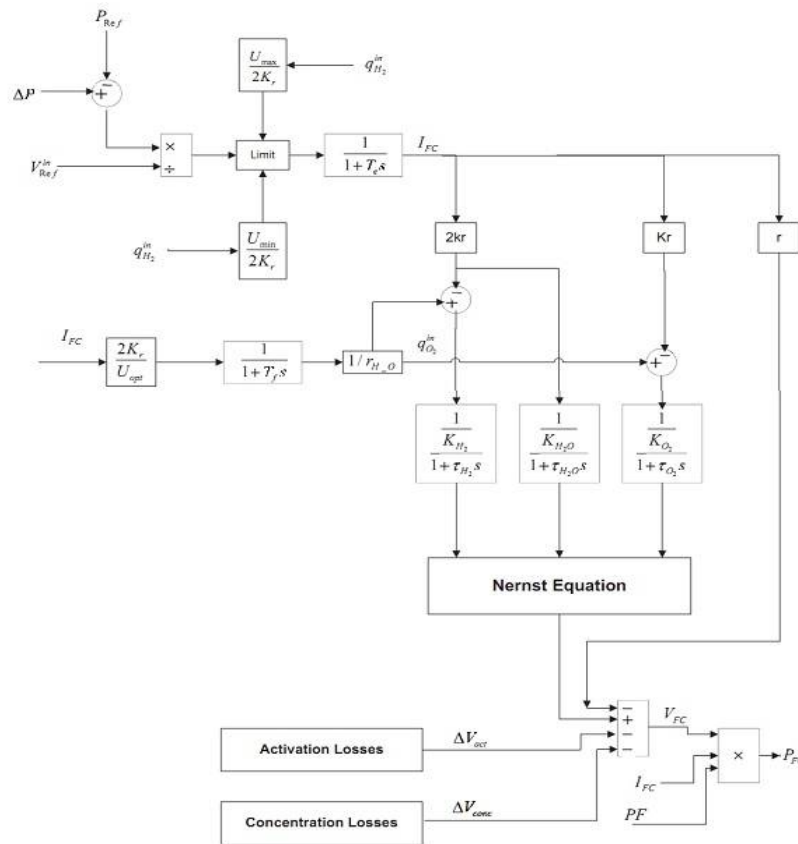


Fig. (2). Mathematical modeling of SOFC

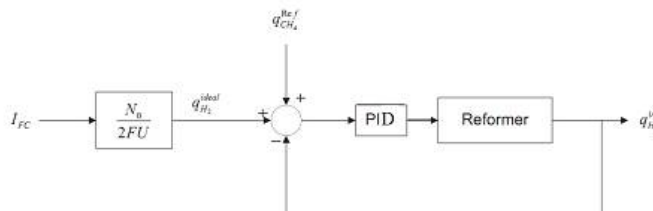


Fig. (3): system with PID controller

and of higher order. Let's consider Fig. (3), the above given unity feedback system, The PID controller is usually implemented as follows:

$$u(t) = k_p e(t) + k_i \int e(t) + k_d \frac{de(t)}{dt} \quad (1)$$



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$$e(t) = y_r(t) - y_m(t) \quad (2)$$

Where k_p , k_i , and k_d are the proportional, the integral, and the derivative gains respectively. The controller output, the process output, and the set point are denoted as $u(t)$, $y_m(t)$ and $y_r(t)$ respectively. A proportional controller (k_p) will have effect of reducing the rise time, but never eliminates the steady-state error. An integral controller (k_i) will reduce the steady-state error but may make the transient response worse. A derivative controller (k_d) will have an effect on stability of the system, it reduces the overshoot, and improving the transient response. To getting the demand power from the system, we first derived the system equation then check its real time response. Then we designed a PID controller to control the close loop function. Ziegler Nichols tuning rule is used to determine the value of k_p , k_i and k_d which is based on the transient step response of a plant. The obtained final values are $k_p = 961.53$, $k_i = 41.25$, and $k_d = 987.56$

IV. SELFTUNING FUZZY CONTROLLER

The performance specifications of the systems such as rise time, overshoot, settling time and error steady state can be improved by tuning parameters k_p , k_i and k_d of the PID controller. By developing self tuning fuzzy controllers, these parameters can be modified online, according to the changes in the process condition without much intervention of an operator.

Lotfi Zadeh, the father of fuzzy logic is extend two valued logic, defined by the binary pair $\{0,1\}$, to the whole continuous interval $[0, 1]$. Fuzzy controllers use heuristic information in developing design the control of nonlinear dynamic system. A fuzzy control system is shown in Fig. 3. FLS is consist fuzzifier, rules, inference engine and output processor (defuzzifier) and that are interconnected. The fuzzifier converts the crisp value into Fuzzy Sets. It is needed to activate rules that are in terms of linguistic variables. The rules are the heart of an FLS. The rules are expressed as a collection of IF-THEN statements. The IF-part of a rule represents antecedent and the THEN part represents consequent. The fuzzified inputs activate the inference engine and the rule base to produce a Fuzzy Set output. The commonly used inferential procedure is minimum and maximum implication method. Defuzzification is necessary to obtain the crisp number as the output.

Here we used self tuning fuzzy PID and PID controller, that is, the three parameters such as proportional gain (k_p), integral gain (k_i) and derivative gain (k_d) of controllers are tuned by using fuzzy tuner. The co-efficient of the classical controllers cannot be properly tuned for the SOFC with unpredictable parameter variation, hence tune automatically the controller parameters such as k_p , k_i and k_d values by using self tuning fuzzy PID controller. The structure of the self tuning fuzzy PID controller is shown in Fig. 4.

The proposed controller structures consist of a simple upper level controller and a lower level classical controller. The upper level controller provides a mechanism to select the gain of a classical PID and the lower level deliver the solution to a particular situation. Here we use the control structure as a rule based Mamdani fuzzy controller. It is used in the upper level and conventional PID controller is selected for the lower level.

In fuzzy structure, there are two inputs to fuzzy inference: error $e(t)$ and change of error $de(t)$ and three outputs for each PID controller parameters respectively k_p , k_i and k_d . The steps for designing aimed controller for the spherical type of storage vessel are as follows:

a) Select the input and output parameters for the fuzzy controller. Here we choose the error signal and the change of error signal as the input parameters and output parameters for the fuzzy controller as the proportional, the integral gain and derivative gain.

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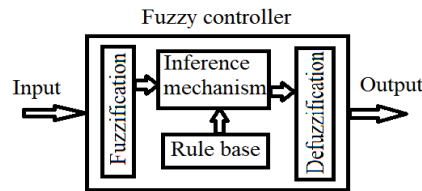


Fig. 3: A fuzzy control system

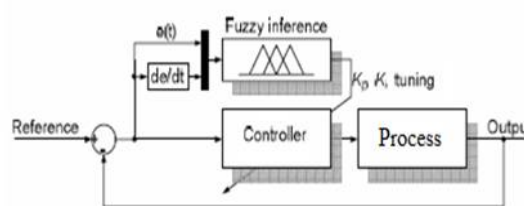


Fig. 4: The structure of the self tuning fuzzy PID controller

b) Then divide the universe of discourse into FSs. Fig. 5 and 6 show the input membership functions for the error signal and change of error signal respectively. Here the universe of discourse is divided as Negative Large (NL), Negative Small (NS), Zero (Z), Positive Small (PS) and Positive Large (PL). Fig. 7 to 9 shows the output membership function for the proportional and the integral gains, whereas the universe of discourses is divided as Medium (M), Big (B) and Very Big (VB).

c) Write the rule base for the Self Tuning Fuzzy PID controller, based on experience and it is described in the below given Table 1 - 3 correspondingly.

d) Use the algorithm of the tuned controller : Centroid defuzzification is the best technique to obtain the crisp output.

The degree of each membership function which was computed in the previous step of fuzzifications encountered by the subprogram called defuzzify and this after certain process it returns defuzzified output.

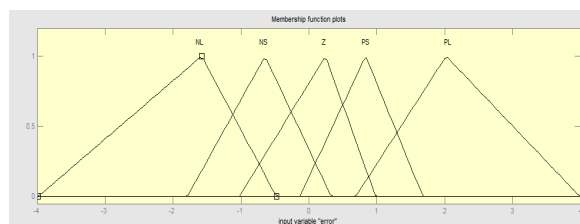


Fig. 5: Membership functions for the error signal

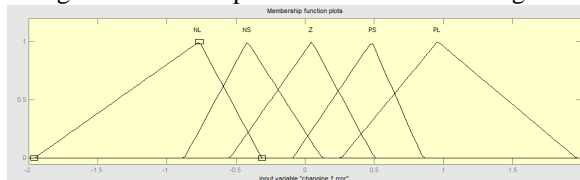
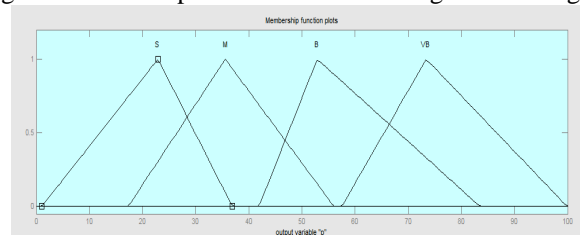


Fig. 6: Membership functions for the change of error signal



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Fig. 7: Membership functions for the proportional gain

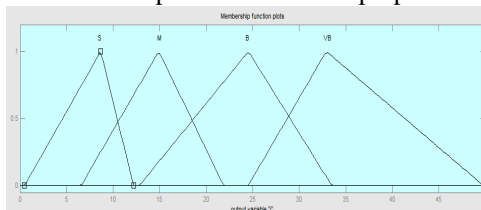


Fig. 8: Membership functions for the integral gain

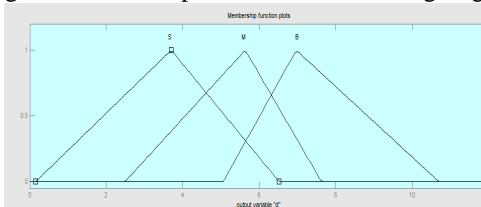


Fig. 11: Membership functions for the derivative gain

TABLE 1: RULE BASE FOR THE PROPORTIONAL GAIN

e	N	N	Z	P	P
Δe	L	S	S	S	L
NL	M	S	S	S	M
NS	B	M	S	M	B
Z	V	B	M	B	V
PS	B	M	S	M	B
PL	M	S	S	S	M

TABLE 2: RULE BASE FOR THE INTEGRAL GAIN

e	N	N	Z	P	P
Δe	L	S	S	S	L
N	B	M	S	M	B
NS	B	M	M	M	B
Z	V	B	M	B	V
PS	B	M	M	M	B
PL	B	M	S	M	B

TABLE 3: RULE BASE FOR THE DERIVATIVE GAIN

e	NL	NS	Z	PS	PL
Δe					
NL	M	M	B	M	M
NS	M	M	B	M	M
Z	S	M	B	M	S
PS	M	M	B	M	M
PL	M	M	B	M	M



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TABLE (2): PARAMETERS IN SOFC SYSTEM MODEL

Parameter	Representation	Value
P_{rate}	Rated power	100 kW
P_{ref}	Real power reference	100 kW
T	Absolute temperature	1273 K
F	Faraday's constant	96487 C/mol
R	Universal gas constant	8314 J/(kmol K)
E_0	Ideal standard potential	1.18 V
N_0	Number of cells in series in the stack	384
K_r	Constant $\frac{N_0}{4F} = K_r$	0.996×10^{-6} kmol/(sA)
U_{max}	Maximum fuel utilization	0.9
U_{min}	Minimum fuel utilization	0.8
U_{opt}	Optimal fuel utilization	0.85
K_{H_2}	Valve molar constant for hydrogen	8.43×10^{-4} kmol/ (s atm)
K_{H_2O}	Valve molar constant for water	2.81×10^{-4} kmol/ (s atm)
K_{O_2}	Valve molar constant for oxygen	2.52×10^{-3} kmol/ (s atm)
τ_{H_2}	Response time for hydrogen flow	26.1 s
τ_{H_2O}	Response time for water flow	78.3 s
τ_{O_2}	Response time for oxygen flow	2.91 s
r	Ohmic loss	0.126 Ω
T_e	Electrical response time	0.8 s
T_f	Fuel processor response time	5 s
r_{H-O}	Ratio of hydrogen to oxygen	1.145
PF	Power factor	1.0
$i_{0,den}$	Exchange current density	20 mA/cm ²
$i_{limit,den}$	Limiting current density	900 mA/cm ²
A	Cell area	1000 cm ²
a	Charge transfer coefficient	0.5
n	number of electrons (per mole); or sample size in statistical tests	2



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V.RESULT

Assume a stand-alone SOFC system is operating with constant rated voltage 1 V and power demand 0.7 Watts. The schematic Simulink diagram is shown Fig (2). All parameters are the same as Table (2). At t=50 s, there is a step increase of power demand from 0.7 to 1.0 Watts.

A OPEN LOOP RESPONSE

The Fig. (12) shows that the open loop response of Pdem, Preal, Vfc, Ifc from the SOFC system. In the first 50 sec after power demand is increased, power real has a rapid increase due to the fast electrical response time in the fuel cells. Subsequently, power real increases slowly and continuously until reaching below the required power. This is due to the slow chemical response time in the fuel processor. The total response time of power real from 0.4 to 0.6 Watts is about 10s.

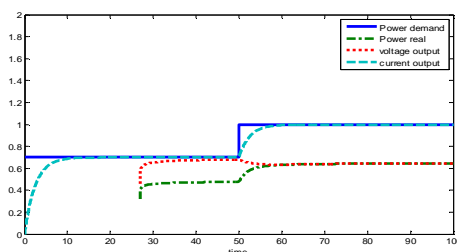


Fig (12): Open loop response of Pdem, Preal, Vfc, Ifc from the SOFC system

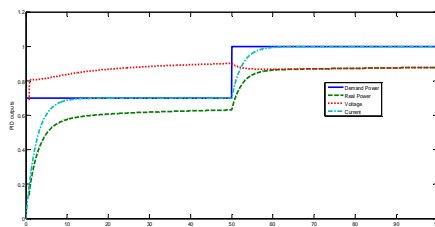


Fig (13): PID response of Pdem, Preal, Vfc, Ifc from the SOFC system

B PID RESPONSE

The Fig. (13) shows that the PID response of Pdem, Preal, Vfc, Ifc from the SOFC system. In the first 50 sec after power demand is increased, power real has a rapid increase due to the fast electrical response time in the fuel cells. Subsequently, power real increases slowly and continuously until reaching below the required power. This is due to the slow chemical response time in the fuel processor. The total response time of power real from 0.6 to 0.85 Watts is about 10 s.

C SELF TUNING FUZZY PID RESPONSE

The Fig. (7) shows that the Selftuning fuzzy PID response of Pdem, Preal, Vfc, Ifc from the SOFC system. In the first 50 sec after power demand is increased, power real has a rapid increase due to the fast electrical response time in the fuel cells. Subsequently, power real increases slowly and continuously until reaching the required power. The total response time of power real from 0.7 to 0.9 Watts is about 10 s.

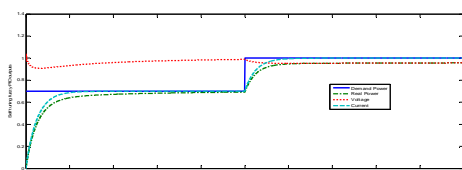


Fig (7): Selftuning Fuzzy PID response of Pdem, Preal, Vfc, Ifc from the SOFC system



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VI.CONCLUSION

In this paper, the SOFC model developed in Matlab/SIMULINK environment is used to simulate the performance of the SOFC fuel cell. The response of the system to step changes in power demand are presented along with the analysis of the simulated results. It has been observed that the fluctuations in the output voltages in the power system due to demand power variations are taken care of by the SOFC very closely. The fuel cell system reduces the cost of power generation as well as the level of pollution. The Simulation results are presented for various dynamic characteristics of the Fuel cell system. The total response time of power real from 0.7 to 0.9 Watts is about 10 s in Self tuning Fuzzy PID controller and from 0.6 to 0.85 Watts is about 10 s in PID controller. The Self tuning Fuzzy PID controller can be considered stronger than PID controllers.

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